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Publication Date
1987-06-03
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March 1987
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Phase-Space Solution of the Linear Mode-Conversion Problem*

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ABSTRACT

The problem of linear mode conversion in a weakly inhomogeneous medium is posed and solved by phase-space methods. The PDEs for the two coupled modes are transformed to a simple first-order ordinary differential equation by a canonical transformation, wherein the two dispersion functions become essentially a locally conjugate pair of coordinates.

*This work was supported by the U.S. Department of Energy under Contract No. DE-AC03-76SF00098.
Wave propagation problems have traditionally been solved either in physical 4-dimensional space-time (x-space) or in terms of Fourier transforms (k-space). Yet, because the Hamiltonian ray equations describe orbits in 8-dimensional phase space, one would expect that more general coordinates would sometimes be of use.

Such is the case in the problem of linear mode conversion, when the components $D_{ij}(k,x)$ of the wave dispersion tensor have spatial variation in different directions [1]. To introduce notation, let us first use reduction techniques [2] to make $D$ a 2x2 matrix field, assumed to be Hermitian:

$$
D(k,x) = \begin{pmatrix}
D_a(k,x) & \eta(k,x) \\
\eta^* (k,x) & D_b(k,x)
\end{pmatrix}.
$$

(1)

Here $D_a$ and $D_b$ are the respective dispersion functions for two modes, $a$ and $b$, while $\eta$ is the (small) coupling. Typically, for a ray of mode $a$, whose orbit is generated by $D_a(k,x)$:

$$
\frac{dx^\mu}{d\sigma_a} = -\frac{\partial D_a}{\partial k^\mu}, \quad \frac{dk^\mu}{d\sigma_a} = +\frac{\partial D_a}{\partial x^\mu}
$$

(2)

and lies on the 7-dimensional manifold $D_a(k,x) = 0$, the other dispersion function $D_b$ is irrelevant, so long as $D_b \neq 0$.

However, if a ray of mode $a$ pierces [at the point $(k_C, x_C)$] the 7-dimensional manifold $D_b(k,x) = 0$, it will transfer wave-action to mode $b$, mediated by the coupling parameter $\eta$. Using x-space eikonal methods, we have shown [2] that the transmission ratio (transmitted intensity/incident intensity) is given by
\[ T = \exp[-2\pi |\eta|^2 / \{\{D_a, D_b\}\}] , \quad (3) \]

in terms of the Poisson Bracket

\[ \{D_a, D_b\} = \frac{\partial D_a}{\partial k^\mu} \frac{\partial D_b}{\partial x^\mu} - \frac{\partial D_a}{\partial x^\mu} \frac{\partial D_b}{\partial k^\mu} , \quad (4) \]

and the coupling \( \eta \), both evaluated at the conversion point \((k_c, x_c)\).

The appearance of the Poisson Bracket (4) in the result (3) suggests that this problem could benefit from phase-space methods. We shall demonstrate that this is indeed the case, allowing for an extremely simple derivation of the result (2).

We first localize the problem about the conversion point, by expanding \( D_a, D_b, \)

and \( \eta \) in a Taylor series, and keep only the leading terms. Thus \( D_a \) and \( D_b \) are linear

in the first derivatives, evaluated at \((k_c, x_c)\):

\[ D_i(k, x) = (\partial D_i / \partial k^\mu) (x - x_c)^\mu + (\partial D_i / \partial x^\mu) (k - k_c)^\mu , \quad (5) \]

while the leading term in \( \eta \) is its value at \((k_c, x_c)\).

The wave field \( Z(x) = (Z_a(x), Z_b(x)) \) satisfies [3] the field equation:

\[ D(k \rightarrow -i \frac{\partial}{\partial x}, x) \circ Z(x) = 0 , \quad (6) \]

which is a set of two coupled linear partial differential equations. The operator

\[ \bar{k} = -i \frac{\partial}{\partial x} \]
\[ [x^\mu, k_\nu] = i \delta^\mu_\nu, \]  

(7a)

corresponding to the Poisson Bracket

\[ \{x^\mu, k_\nu\} = \delta^\mu_\nu. \]  

(7b)

A general canonical change of coordinates has the form:

\[ (i = 1, 2, 3, 4) \quad q_i = q_i(k, x), \quad p_i = p_i(k, x), \]  

(8a)

with

\[ \{q_i, p_j\} = \delta_{ij}. \]  

(8b)

Then the Hamiltonian equations are form invariant, and we have, for mode \( a \),

\[ \frac{dq_i}{d\sigma_a} = - \frac{\partial \overline{D}_a(q,p)}{\partial p_i}, \quad \frac{dp_i}{d\sigma_a} = + \frac{\partial \overline{D}_a(q,p)}{\partial q_i}, \]  

(9a)

where \( \overline{D}_a(q,p) \) is the original dispersion function in terms of the new variables:

\[ \overline{D}_a(q,p) = D_a(k, x). \]  

(9b)

Let us now choose
\[ p_1(k,x) \equiv -D_a(k,x) ; \]  

i.e., \( \overline{D}_a(q,p) = -p_1 \). Then (9a) yields

\[ \frac{dq_i}{d\sigma_a} = 1, \quad \frac{dq_i}{d\sigma_a} = 0 \ (i \neq 1), \quad \frac{dp_i}{d\sigma_1} = 0 ; \]  

in other words, \( q_1 \) is the orbit parameter of mode \( a \).

Next we choose

\[ q_1(k,x) = \alpha D_b(k,x) , \]  

with \( \alpha \) a constant determined by (8b): \( \{q_1, p_1\} = 1 \). This yields \( \alpha = B^{-1} \), where \( B = \{D_a, D_b\} \) evaluated at \( (x_c, k_c) \). Then, similarly to (11), we have

\[ \frac{dp_1}{d\sigma_b} = B, \quad \frac{dp_i}{d\sigma_b} = 0 \ (i \neq 1), \quad \frac{dq_i}{d\sigma_b} = 0 ; \]  

i.e., \( p_1 \) is (within the factor \( B \)) the orbit parameter of the converted ray of mode \( b \). Thus \( q_1 \) and \( p_1 \) are not only conjugate, but are the natural phase-space coordinates based on the two rays.

The dispersion matrix now reads

\[ \overline{D}(p,q) = \begin{pmatrix} -p_1 & \eta \\ \eta^* & Bq_1 \end{pmatrix} \]  

(14)
The field equation (6) now reads

\[
\mathbb{D} (p \to -i \frac{\partial}{\partial q}) \cdot \mathbf{Z} (q) = 0 ,
\]  

(15)

where \( \mathbf{Z}(q) \) is related to \( \mathbf{Z}(x) \) by a metaplectic transformation [4], which need not concern us here.

Using (14) in (15), we have

\[
\begin{align*}
\left\{ \begin{array}{l}
\bar{\eta} \frac{\partial \mathbf{Z}_a(q)}{\partial q_1} + \gamma \mathbf{Z}_b(q) &= 0 , \\
\gamma^* \mathbf{Z}_a(q) + Bq_1 \mathbf{Z}_b(q) &= 0
\end{array} \right.
\]  

(16a)

(16b)

Eliminating \( \mathbf{Z}_b \), we have the first-order ordinary differential equation:

\[
\frac{\partial \mathbf{Z}_a(q)}{\partial q_1} = (i|\gamma|^2/Bq_1)\mathbf{Z}_a(q) ,
\]  

(17)

whose solution is

\[
\mathbf{Z}_a(q) = f(q_2, q_3, q_4)q_1^{i|\gamma|^2/B} ,
\]  

(18)

with \( f \) arbitrary.

The amplitude transmission ratio \( R \) is defined to be

\[
R \equiv \frac{\mathbf{Z}_a(+ q_1, q_2, q_3, q_4)}{\mathbf{Z}_a(- q_1, q_2, q_3, q_4)} ;
\]  

(19)
i.e., the amplitude of mode $a$ is compared at equal $|q_1|$ distances from the conversion point $q_1 = 0$. From (18) we find

$$R = (-1)^{|m|/B} = \exp\left(\pm \pi |m|/B\right).$$  \hfill (20)

Choosing the proper sign for causality, we finally obtain

$$T = |R|^2 = \exp[-2\pi |m|^2/|B|].$$ \hfill (21)

Comparison of this derivation with our previous x-space approach shows how remarkably simple the phase-space method is.

We are indebted to Robert Littlejohn for introducing us to metaplectic techniques.
References

This report was done with support from the Department of Energy. Any conclusions or opinions expressed in this report represent solely those of the author(s) and not necessarily those of The Regents of the University of California, the Lawrence Berkeley Laboratory or the Department of Energy.

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