Optimal Insurance with Costly Internal Capital

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Abstract

We introduce costly internal capital into a standard insurance model, in which a risk-averse policy holder buys insurance from a risk-neutral insurer with limited liability. We show that the optimal contract is unique, and leads to a positive probability for insurer default. Some risks are uninsurable, in the sense that it is optimal for the insurer not to provide insurance against such risks. We characterize when such situations arise, as a function of the properties of the risk, the cost of internal capital, and the policy holder’s utility function. An increase in the cost of capital may lead to a higher optimal amount of internal capital. The results continue to hold when there are multiple policy holders who are exposed to identical risks. This extension of the classical model to include costly internal capital provides a fruitful approach to many real world insurance markets.
1 Introduction

If insurers hold sufficient capital, they can make a credible guarantee to pay all claims. As shown in the seminal analysis by Arrow (1963),\(^1\) the optimal insurance contract between a risk neutral insurer and a risk averse policy holder in this case is full coverage against losses above a strictly positive deductible. In practice, two factors together make such a contract infeasible. First, virtually all insurers are now limited liability corporations, which eliminates the unlimited recourse to partners’ external (private) assets that was once common.\(^2\) To avoid counterparty risk, a large amount of capital therefore needs to be held within the firm. Second, the excess costs of holding internal (on balance sheet) capital, such as corporate taxes, asymmetric information, and agency costs, provide a strong incentive for insurers to limit the amount of such capital they hold.

The excess costs of holding internal capital, e.g., in the form of lost tax shields, have long been studied in the corporate finance literature, see, e.g., Modigliani and Miller (1963), and more recently Froot, Scharfstein, and Stein (1993), and Froot and Stein (1998). For insurance firms, Cummins (1993), Merton and Perold (1993), Jaffee and Russell (1997), Myers and Read (2001), and Froot (2007) all emphasize the importance of various accounting, agency, informational, regulatory, and tax factors in raising the cost of internally held capital. Zanjani (2002) argues that the cost of internal capital may be especially important for catastrophic insurance. In practice, policyholders therefore face counterparty risk.

The risk of insurer default in paying policyholder claims has led to the imposition of strong regulatory constraints on the insurance industry in most countries. Capital requirements are one common form of regulation, although no systematic framework is available for determining the appropriate levels.\(^3\) As Cummins (1993) and Myers and Read (2001) point out, it is likely that the capital requirements are being set too

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\(^1\)See also Arrow (1971) and Arrow (1974).

\(^2\)The insurer Lloyds of London once provided a credible guarantee to pay all claims, based on the private wealth of its “names” partners. In the aftermath of large asbestos claims, however, Lloyds now operates primarily as a standard “reserve” insurer with balance sheet capital and limited liability.

\(^3\)Insurance guaranty funds represent a second form of regulation that attempts to control the risk of insurer default. These funds are required in many states for consumer lines, principally homeowner and auto insurance. All of the insurers participating in the line are required to provide funds to meet policyholder claims in case another insurer has failed. While the guaranty funds may reduce the risk of insurer default by diversifying the risk, Cummins (1988) points out that even for the applicable lines, policyholders still face substantial default costs since the guaranty funds usually impose a maximum payment per claim and because the payments may be substantially delayed as the claims are transferred from the bankrupt insurer to the guaranty fund.
high in some jurisdictions and too low in others, and similarly for the various lines of insurance risk, in both cases leading to inefficiency. It is thus important to have an objective framework for identifying the appropriate level of capital based on each insurer’s particular book of business. In this paper, we provide such a framework.

We study the design and properties of an optimal contract in a competitive insurance market, between a risk neutral insurer and a risk averse policy holder, when the insurer has limited liability and internal capital is costly. The model endogenously determines the optimal level of the deductible, the policy premium, and the capital held by the insurer (which in turn determines the states in which the insurer defaults). To our knowledge, the optimal contract and its characteristics under these conditions have not been previously studied. Some features of the optimal contract turn out to be consistent with the previous literature, whereas others are new.

The optimal contract itself is shown — in line with previous literature — to be one with a deductible. Above the deductible, full insurance is available until all internal capital is used; above that point the insurer defaults. The optimal contract thus depends on two parameters: the deductible and the amount of internal capital. The insurance contract can be viewed as the difference between a call option for the policy holder on the loss with the strike price being the deductible, and a call option for the insurer to default, with the strike price being the sum of internal capital and the deductible. Using standard option pricing arguments, we characterize the premium charged for the insurance.

For any given (strictly positive) level of internal capital, the deductible is shown to be unique, and there is a unique level of internal capital that leads to a globally optimal contract. This contract is associated with a strictly positive probability of insurer default. As long as the cost of internal capital is lower than the amount of capital held, no risk is totally uninsurable in the sense that there will always be some policy holder preferences for which insurance demand is positive. An increase in the cost of internal capital can lead to either an increase or decrease of the deductible, as well as of the amount of internal capital. For the special case when losses have a two-point distribution, the analysis simplifies significantly. We provide a full characterization of the solution for this specific case.

introduce a method to analyze whether the optimal deductible is unique. None of these studies consider the case with limited liability, which is the focus of our study. Doherty and Schlesinger (1990) analyze the optimal insurance in case of possible insurer default, but default is modeled as an exogenous event in their paper, as is the case in Cummins and Mahul (2003), Mahul and Wright (2004), and Mahul and Wright (2007). Cummins and Mahul (2004) allow for an upper bound on compensation, e.g., because of limited liability, but treat this bound as exogenous. Our analysis is most closely related to Cummins and Mahul (2004), with our contribution being that internal capital is costly in our model and that we solve for the optimal amount of capital for the insurer to hold. Huberman, Mayers, and Smith (1983) study optimal contracts when the policy holder has limited liability. Their setting is thus different from ours. Kaluszka and Okolewski (2008) allow for a general cost function that depends both on expected losses and maximal claims, but do not cover our case where costly internal capital is the sole source of extra costs of insurance. Doherty, Laux, and Muermann (2011) show that when losses are non-verifiable, upper bounds on compensation naturally arise. Thus, their optimal contract is similar to ours, but their mechanism is quite different.

The assumption of a single policyholder has been commonly used in the insurance literature, including Arrow (1963), but may seem restrictive in this setting. However, the assumption may best be viewed as the policy holder being a “representative agent” for multiple policy holders, a common approach used in both the finance and insurance literatures. This interpretation is especially straightforward if the multiple policy holders face highly correlated risks — effectively the same risk. In this case, the single policy holder model can be directly reinterpreted as representing the (aligned) utilities of all agents. Insurance against natural disasters, like earthquakes, provides an example where such an interpretation is fairly straightforward.

More generally, one would expect the representative agent interpretation to be valid in situations where policy holders are “symmetric” in their preferences and the risks they face. We provide an example of such a generalized interpretation, where many policy holders with identical preferences insure identical risks with an insurer, and show that our main results extend to this setting too. Thus, our single policy holder model is not restrictive in a variety of relevant cases.

The paper is organized as follows: In Section 2, we introduce an insurance model with costly internal capital and analyze the optimal contract and premium given an exogenously specified level of internal capital. In Section 3, we endogenize the level of internal capital, and in Section 4 we discuss discrete loss distributions, specifically
focusing on the two-point distribution. In Section 5 we extend the general results to an example with multiple policy holders. Finally, Section 6 concludes.

2 A model with costly internal capital

At \( t = 0 \), an insurer (i.e., an insurance company) in a competitive insurance market sells insurance against an observable idiosyncratic risk, \( \tilde{L} \geq 0 \) (throughout the paper we use the convention that losses take on positive values) to an insuree. We assume that \( \tilde{L} \) has an absolutely continuous distribution, with a strictly positive probability density function, \( \varphi(x) \), on the positive real axis.\(^4\) We also define the complementary cumulative distribution function \( \Phi(x) = \int_x^\infty \varphi(y)dy \).

The risk is realized at \( t = 1 \), at which point the insurer makes a payment of \( I(\tilde{L}) \) to the insuree. We call \( I \) the compensation (indemnity) function. The expected loss of the risk is \( \mu_L = E[\tilde{L}] < \infty \). We will use the notation \( \mu_X = E[X] \) for a general random variable, \( X \). The one-period discount rate is normalized to 0.

The insurer, which has limited liability, reserves capital of \( A \) within the company, and the maximal payment it can make is therefore bounded by \( A \). Further, in line with the literature we assume that the compensation must be nonnegative and not greater than \( \tilde{L} \). Thus, the constraint on the compensation function is:

\[
0 \leq I(\tilde{L}) \leq \min(\tilde{L}, A). \quad (1)
\]

Holding internal capital is costly. We assume that there is a proportional cost, so that the cost of holding \( A \) is \( \delta A \), \( 0 < \delta < 1 \). This is in line with a tax shield interpretation of what is the source of costly internal capital. Several of our results can be generalized to weakly convex cost functions, in line with the assumptions in Froot (2007). The insurer is risk-neutral and the market is competitive, so the premium, \( P \), paid by the insuree for insurance is

\[
P = E[I(\tilde{L})] + \delta A. \quad (2)
\]

The insuree has a twice continuously differentiable expected utility function, \( u \),

\(^4\)Extensions to more general distributions are discussed further on in the paper.
defined on the negative real axis, such that $u' > 0$ and $u'' < 0$. Further, we assume that $|Eu(-\tilde{L})| < \infty$, i.e., that the insuree’s expected utility of taking on the whole risk is finite, as well as the technical conditions $|Eu'(-\tilde{L})| < \infty$, and $|Eu''(-\tilde{L})| < \infty$.

Because of the competitive market, the insurer aims at offering an optimal insurance contract leading to the following optimization problem:

$$\max_{I(\tilde{L}), A} E \left[ u(-\tilde{L} + I(\tilde{L}) - P) \right], \text{ s.t. } (1) \text{ and } (2).$$

As noted, this problem formulation has similarities to that in Cummins and Mahul (2004), but differs by introducing costly internal capital and by endogenizing $A$. The same is true for the formulation in Kaluszka and Okolewski (2008), who consider pricing functions of the form $P = (1 - \delta)E[I(\tilde{L})] + \delta A$, $0 < \delta < 1$. However, in our setting there is no $\delta$ in the first term on the right hand size of (2).

The following result shows that, given internal capital of $A$, the optimal contract is a standard insurance contract with a deductible, above which all residual risk is insured until the limited liability constraint is reached.

**Proposition 1** The optimal insurance contract, given internal capital of $A > 0$, is

$$I(\tilde{L}) = \begin{cases} 0, & \tilde{L} \leq D, \\ \tilde{L} - D, & D < \tilde{L} \leq D + A, \\ A, & \tilde{L} > D + A, \end{cases}$$

for some unique $D > 0$, which depends continuously on $A$.

In case $\tilde{L} > D + A$, the insurer is said to default. The optimal contract can thus be viewed as a “stop-loss” contract with a deductible.

This result is similar to what is shown in Cummins and Mahul (2004), the only difference being our assumption about costly internal capital. We could have taken their approach of proving it, by using the method in Meyer and Ormiston (1999) of reformulating the problem in terms of expected compensation. Instead, we prove the result (see the appendix), using the direct problem formulation since this makes the mechanism behind the result more transparent.
The optimal insurance contract is thus characterized by a deductible $D$ and the amount of internal capital, $A$. Since $D$ is unique for each choice of internal capital, $A > 0$, we may also view $D$ as a function of $A$ and write $D(A)$. The first order condition for $D$ will be analyzed in the next section — and is fairly complicated. For low levels of internal capital $A$, however, the characterization of the optimal $D$ is simple. We define

$$\mu_{\omega} = E[u'(-\bar{L})],$$

and it then follows that

**Proposition 2** As $A$ tends to 0, the optimal deductible, $D$ tends to $\bar{D}$, defined as the solution to

$$u'(-\bar{D}) = \mu_{\omega}.$$  \hspace{1cm} (4)

Thus, for low levels of internal capital, the deductible is chosen such that the marginal utility of a loss equal to the deductible is basically equal to the expected marginal utility without insurance. The left hand side of (4) represents the increase in marginal utility of decreasing the deductible, per unit of internal capital. The right hand side of (4) represents the offsetting decrease of marginal utility from a higher premium when the deductible is decreased. At the optimum, $\bar{D}$, the two effects are equal. We note that since $u'$ is strictly decreasing, there is a unique solution to (4).

Technically, the optimal contract is degenerate when $A^* = 0$, since any $D$ leads to the same outcome — namely that the risk is uninsured. We disregard this degeneracy of the contract at $A = 0$, and use the convention that $A = 0, D = \bar{D}$ is the contract that corresponds to no insurance. This convention leads to continuity of $D(A)$ at $A = 0$.

The optimal contract can be viewed as the difference between two call options, one call option by the insuree to get payments net the deductible, $W(D) = \max(\bar{L} - D, 0)$ and one call option by the insurer to default, $Q(A) = \max(\bar{L} - D - A, 0)$, so that in total

$$I(\bar{L}) = W(D) - Q(A).$$
Thus, the premium can be written

\[ P = P(A, D) = \mu_W - \mu_Q + \delta A. \]

The following behavior of the premium as a function of \( D \) and \( A \) then follows immediately from standard option pricing theory:

**Proposition 3** The insurance premium, \( P(A, D) \) satisfies the following conditions:

1. \( P(0, D) = 0 \),

2. \( \lim_{A \to \infty} P(A, D) - \delta A = \mu_W \), for all \( D \),

3. \( \lim_{D \to \infty} P(A, D) = \delta A \), for all \( A \),

4. \( \frac{dP}{dA} = \delta + \Phi(A + D) > 0 \),

5. \( \frac{dP}{dD} = -\Phi(D) + \Phi(D + A) < 0 \),

6. \( \frac{d^2P}{dA^2} = \frac{d^2P}{dDdA} = -\varphi(A + D) < 0 \),

7. \( \frac{d^2P}{dD^2} = \varphi(D) - \varphi(D + A) \geq 0 \).

Under the additional condition that the probability density function, \( \varphi \), is strictly decreasing, the sign of \( \frac{d^2P}{dD^2} \) is unambiguous,

\[ \frac{d^2 P}{dD^2} > 0. \]

Thus, the premium is well characterized.
3 Optimal internal capital

Given the form of the optimal insurance contract in Proposition 1, and defining $F = Eu(-\tilde{L} + I(\tilde{L}) - P)$, it follows that the first order conditions in (1) are given by

$$0 = \frac{\partial F}{\partial A} = \alpha - (\delta + \Phi(D + A))(\alpha + Zu'(-D - P) + \beta),$$  \hspace{1cm} (5)

$$0 = \frac{\partial F}{\partial D} = Z\alpha - Z(1 - Z)u'(-D - P) + Z\beta,$$  \hspace{1cm} (6)

where

$$Z = \Phi(D) - \Phi(D + A),$$

$$\alpha = \int_{D+A}^{\infty} u'(-x + A - P)\varphi(x)dx,$$

$$\beta = \int_{0}^{D} u'(-x - P)\varphi(x)dx.$$

The first order condition with respect to $D$, (6), is necessary for an interior solution, and from Proposition 1 it is sufficient.

By rearranging the terms in (6), we arrive at

$$u'(-D - P) = \alpha + Zu'(-D - P) + \beta,$$  \hspace{1cm} (7)

as the first order condition in $D$ for any given $A$. When plugged into (5), this leads to

$$\alpha = (\delta + \Phi(D + A))u'(-D - P),$$  \hspace{1cm} (8)

as a necessary condition for a globally optimal interior solution. Condition (8) relates the insuree’s marginal utility at the point where the insurance contracts begins to pay, $-D - P$, to the average marginal utility in states of default, adjusted for the extra costs of internal capital, $\frac{1}{(\delta + \Phi(D + A))} \int_{D+A}^{\infty} u'(-x + A - P)\varphi(x)dx$. For a contract to be optimal they need to be equal, because otherwise the insuree can be made better off by changing $A$ and $D$. We denote the optimal value(s) of the internal capital and deductible by $A^*$ and $D^*$, respectively.

From the facts that uninsured expected utility is finite, $|Eu(-\tilde{L})| < \infty$, and that
the premium grows without bounds for large $A$ (see (2)), it follows that $A^* = \infty$ cannot be a formal solution, but given the nonconcave behavior of the compensation function, $I$, and the premium, $P$, we would a priori not expect the optimal insurance contract to necessarily be either unique, nor interior. In general, we would expect solutions on the form

1. $A^* = 0$, $D^* = \bar{D}$, i.e., the risk is not insured, or

2. $A^* > 0$, $D^* = D(A^*) > 0$, for one or several levels of internal capital, $A^* > 0$,
or both. The following proposition shows, somewhat surprisingly, that the optimal contract is actually unique:

**Proposition 4** There is a unique optimal contract, i.e., there are unique levels of internal capital, $A^* \geq 0$, and deductible, $D^* > 0$, such that the stop-loss contract with deductible defined in Proposition 1 is the optimal contract.

As shown in the proof of the proposition, the uniqueness of the optimal contract follows from the fact that the Hessian of $F$, as a function of $D$ and $A$, is strictly negative definite at any point where the first order conditions for optimality are satisfied. This property of the Hessian is in general not sufficient to imply uniqueness for multivariate functions, but because the optimal $D$ is unique as a function of $A$ and depends smoothly on $A$ (see Proposition 1) it turns out to be sufficient in this case.

We next analyze when the optimal contract is interior. We use the following terminology: If there is a solution with $A^* > 0$, then insurance is said to be optimal, whereas if the only solution is the one with $A^* = 0$, then insurance is said to be suboptimal. The following proposition characterizes when insurance is optimal:

**Proposition 5** Define

$$\xi = \frac{1}{2} \frac{E[|u'(\bar{L}) - \mu_{u'}|]}{\mu_{u'}}.$$  \hspace{1cm} (9)

Then,

1. if $\delta > \xi$, insurance is suboptimal, whereas
2. if $\delta < \xi$, insurance is optimal.

Thus, in addition to the cost of internal capital, $\delta$, both risk distributions and insuree preferences (through (9)) are in general crucial in determining whether insurance is optimal for a specific insuree.

If, for a specific risk, insurance is suboptimal for all risk averse agents, the risk is said to be uninsurable. It turns out that insurability only depends on the cost of internal capital, not on the specific risk distribution, as shown by the following proposition:

**Proposition 6** If $\delta \geq 1$ every risk is uninsurable, whereas if $\delta < 1$ no risk is uninsurable.

The case $\delta \geq 1$ is obviously extreme since it implies that the insuree’s premium is higher than the maximum insurance claim. It is unsurprising that in this case, risks are always uninsurable. But Proposition 6 also provides a positive case for insurance in that it shows that as long as there is any chance that the claim is higher than the premium, insurance will be optimal for some severely risk averse insurees. This is the interesting part of the proposition.

If insurance is optimal, the optimal contract implies a positive probability for insurer default. This is, of course, trivial since $A^* < \infty$ and, per assumption, the loss distribution has support on the whole of the positive real axis. However, it is less trivial that this property generalizes to situations where the loss distribution has bounded support, as shown by the following proposition:

**Proposition 7** If $\Phi(\bar{L}) = 0$ for some $\bar{L} < \infty$, i.e., there is a finite upper bound on losses, then $D^* + A^* < \bar{L}$, i.e., the optimal insurance contract leads to a strictly positive risk of insurer default.

The result is dual to the classical result of positive deductibles (Arrow 1963): The optimal contract cuts off payments for small losses through the deductible, as well as for large losses through insurer default. This new result is at first sight less intuitive than the result on deductibles though. The positive deductible is easily motivated, since the utility cost for the insuree of a very small loss is a second order effect compared
with the cost of lowering the deductible which is of first order. Therefore, having a zero deductible is never optimal. In other words, the benefits of decreasing the deductible toward zero occur in the part of the state space where they matter the least to the insuree, but the costs are incurred over the whole state space, through a higher premium.

Such an argument is clearly not valid for the level of internal capital. In fact, increasing $A$, such that $A + D$ approaches $\bar{L}$ decreases the risk in exactly the states that matter the most, close to $\bar{L}$. The way to see that it can never be optimal to choose a contract such that $A + D = \bar{L}$, as shown in the proof of the proposition, is to focus on the deductible, not on the capital. Indeed, as shown in the proposition, the deductible is “too high,” when chosen such that $A + D = \bar{L}$. By decreasing the deductible, more insurance is provided in the high marginal utility states in which losses are higher than the deductible, whereas the cost of an increased premium decreases the utility in the low marginal utility states, below the deductible. When there is a positive probability for default, there is also a third effect, namely that the higher premium decreases the utility in the worst states of default (when $\tilde{L} > A + D$), but when the starting point is one in which default does not occur, $A + D = \bar{L}$, this is effect is of second order, and a slight decrease of $D$ is therefore always optimal. Thus the result.

A standard argument for why insurer default may occur is that under diversification of a finite number of risks there is still some residual risk that there will be so many bad outcomes that there is not enough internal capital to cover all claims. Thus, an insurer may default as a result of less that complete diversification. The argument above does not depend on diversification, since there is only one risk insured, and thus provides another rationale for why insurer default in some states of the world may be (ex ante) optimal.

The comparative statics of $A^*$ and $D^*$ with respect to changes in cost of internal capital, $\delta$, are in general ambiguous:

$$\frac{dA^*}{d\delta} \geq 0, \quad \frac{dD^*}{d\delta} \geq 0.$$ 

An example is given in the next section.

However, in the case when the optimal deductible is small, an increase in $\delta$ can be shown to always decrease the optimal level of internal capital, in line with the intuition that higher costs of internal capital make insurance less attractive. Similar results are obtained for high costs of internal capital, $\delta$. We have
Proposition 8 If $\delta \geq 1 - \Phi(D^*)$, then $\frac{dA^*}{ds} < 0$.

4 Discrete distributions

In the previous analysis, absolute continuity of the distribution functions was assumed. When loss distributions are discrete, somewhat different results may arise. We first study the simplest case, in which the risk that has a two-point distribution, $\tilde{L} \in Be(\bar{L}, p)$, i.e., when $\tilde{L}$ takes on value $\bar{L} > 0$ with probability $p$ and 0 with probability $1 - p$. This case is especially simple, since the optimization problem in Proposition 1 is concave in this case, allowing for a complete characterization of the solution. Of course, it is without loss of generality that we assume that one of the outcomes is 0, since any positive loss that occurs for sure will be internalized by the insuree, who would never choose to “insure” against a certain loss when internal capital is costly. We note that in this case, it is sufficient for the utility function, $u$, to be defined on the interval $[-\bar{L}, 0]$, for the problem to be well defined.

Since the payout is never higher than $\bar{L} - D$ regardless of $A$, and capital is costly, it will never be optimal to reserve more capital than $\bar{L} - D$, i.e., $A + D \leq \bar{L}$. Further, since the payout is the same in all states of the world for all deductibles $D \leq \bar{L} - A$ (in the bad state the insurer defaults and pays $A$, in the good state no payments are made), we will without loss of generality assume that $D = 0$. The technical reason why the optimal $D$ may not be unique, nor strictly positive, in this case — in contrast to what is implied by Proposition 1 — is that probability density function of $\tilde{L}$ is not strictly positive close to 0, as assumed previously, and this makes the first order condition degenerate. We recall that the insuree’s absolute risk aversion at wealth level $x$ is defined by $\text{ARA}(x) = -\frac{u''(x)}{u'(x)}$. We then have

Proposition 9 Let $\tilde{L} \sim Be(\bar{L}, p)$. Then the optimal amount of internal capital, $A^*$, is unique and satisfies

1. $0 \leq A^* < \bar{L}.$
2. Insurance is suboptimal, \( A^* = 0 \), if and only if

\[
\frac{u'(-\bar{L})}{u'(0)} \geq \frac{1 - p}{p} \times \frac{\delta + p}{1 - \delta - p}.
\]

3. \( A^* \) is increasing in \( \bar{L} \), \( \frac{dA^*}{d\bar{L}} > 0 \).

4. For an insuree with decreasing absolute risk aversion (DARA), the value of the insurer’s option to default is increasing in \( \bar{L} \), \( \frac{dA^*}{d\mu Q} > 0 \).

5. For an insuree with increasing absolute risk aversion (IARA), the value of the insurer’s option to default is decreasing in \( \bar{L} \), \( \frac{dA^*}{d\mu Q} < 0 \).

6. Given that, \( A^* > 0 \), then \( \frac{dA^*}{ds} > 0 \), if and only if

\[
ARA((1 - p - \delta)A^* - \bar{L}) - ARA((-p - \delta)A^*) > \frac{1}{A^*(p + \delta)(1 - p - \delta)}.
\]

Proposition 9 thus shows that for this specific type of discrete distribution, the optimal amount of internal capital is still unique, that more internal capital will be held for larger risks, and that depending on the risk aversion of the insuree, the value of the insurer’s option to default can be either larger or smaller for larger risks. Further, the proposition shows that full insurance is never optimal, since condition 1 implies states that \( A^* < \bar{L} \). This is in line with the result in the previous section of a positive probability for insurer default. The interpretation is slightly different here though, because of the degeneracy of the chosen deductible. Specifically, our convention is that \( D = 0 \), and \( A^* < \bar{L} \) then implies a positive probability of default. However, an equivalent contract (leading to the same compensation in all states of the world) is to choose \( D = \bar{L} - A^* \), which never leads to default. Thus, it is only in the case when \( A \geq \bar{L} \) that the situation is unambiguous. In this case default never occurs.

Condition 3 shows that increasing the severity of the risk, in the sense of the magnitude of the bad outcome, leads to a higher level of internal capital. This result depends on the specific definition of “increased risk.” Another definition of risk is in the
sense of second order stochastic dominance. We study the risks \( \tilde{L} \in Be(\bar{L}/p, p) \), \( \bar{L} > 0 \), \( 0 < p < 1 \), which when \( p \) varies all have expected value \( E[\tilde{L}] = \bar{L} \), but have higher risk for higher \( p \) in terms of second order stochastic dominance. It is easy to check that \( \frac{dA^*}{dp} \gtrless 0 \), depending on the utility and risk distribution. Thus, the relationship between risk and level of internal capital is ambiguous when second order stochastic dominance is used even in this simple case.

Condition 6 implies that nonincreasing absolute risk aversion (NIARA) is sufficient for the amount of internal capital to be decreasing in the cost of holding internal capital (since \( A^* < \bar{L} \), so \( (1 - p - \delta)A^* - \bar{L} < (-p - \delta)A^* \)). It is straightforward to construct examples with DARA preferences such that \( \frac{dA^*}{d\delta} < 0 \).

For general discrete \( N \)-point risk distributions, the results results become more complex. The multiplicity of optimal contracts also hold with \( N \)-point distributions, as long as the support of the distribution does not lie within \( D^* \) and \( D^* + A^* \). Specifically, if the support of \( \tilde{L} \) lies on \( \ell_1 < \ell_2 < \cdots < \ell_N \), then if \( \ell_i < D^* < D^* + A^* < \ell_{i+1} \) for some \( i \), then any other \( D' \neq D \) such that \( \ell_i < D' < D' + A^* < \ell_{i+1} \) leads to identical payouts in all states of the world and is therefore also optimal. If \( \ell_i < D^* < \ell_{i+1} < D^* + A^* \), on the other hand, any change in \( D^* \) also changes the claim function in some states of the world.

## 5 Multiple policyholders

As mentioned, we expect similar results to hold more generally when there are multiple policy holders, who insure risks that are not perfectly correlated. For tractability, we study a special case, with many risks that are symmetric Bernoulli distributed, and with policy holders who have identical preferences, and show that the optimal contract in this setting has a similar form as before.

There are \( N \) risk averse policy holders, indexed by \( i = 1, 2, \ldots, N \), who each face a random loss

\[
\tilde{L}_i = \begin{cases} 
0, & \text{with probability } p, \\
1, & \text{with probability } 1 - p,
\end{cases}
\]

for some probability \( 0 < p < 1 \) that is the same for all policy holders. All policy holders have identical preferences, represented by the strictly concave expected utility function

\(^5\)An example is given by \( \delta = 0.6 \), \( p = 0.02 \), \( \bar{L} = 1 \), \( u(x) = -(x + 1.1)^{-5} \), for which \( A^* = 0.6335 \) and \( \frac{dA^*}{d\delta} = -0.0058 \).
The average realized loss per policy holder is defined as $\bar{X} = \frac{1}{N} \sum_i \bar{L}_i$. This is of course also the fraction of policy holders suffering losses, since each loss is equal to unity.

The complementary cumulative distribution function of $\bar{X}$ is $\Phi$. In the appendix, we show how any absolutely continuous average loss function can be generated by an increasing number of symmetric, dependent, Bernoulli distributions as the number of risks, $N$, tends to infinity. Moreover, in this limit, the distribution of $\bar{X}$ is independent of the realization of any one risk, $\bar{L}_i$. As before we assume that the probability density function of $\bar{X}$, $\varphi$, is strictly positive on $[0, 1]$.

The insurer reserves capital of $A$ per policy holder, and signs a contract with each policy holder that pays out $I_i(\bar{L}_i, \bar{X})$ to the $i$th policy holder in case of individual loss of $\bar{L}_i$ and average loss of $\bar{X}$. We define the maximum average payout per policy holder, $\overline{A} = \frac{A}{\bar{X}}$. Because of the strictly concave utility and the symmetry of the setup, it follows immediately that any outcome where the insurer ex ante signs different contracts with different policy holders with the same losses is inferior, i.e., it can be improved upon in a Pareto sense. So we restrict our attention to symmetric outcomes, i.e., outcomes in which the insurer signs identical contracts with all policy holders, $I_i \equiv I$ for all $i$. The feasibility restriction on this contract is then

$$0 \leq I(\bar{L}_i, \bar{X}) \leq \min(\bar{L}_i, \overline{A}).$$

This restriction is similar to the one before: the payoff is bounded below by 0, and above by the actual losses for each insurer and, also, (average) insurance claims can not be higher than (average) capital reserved. The difference compared with previous sections is that the maximum payout needs to be defined taking into account total losses of all policy holders, $\bar{X}$, instead of as before only with respect to the loss of an individual policy holder, $\bar{L}_i$.

We now have the following result:

**Proposition 10** Given internal capital, $A$, the optimal insurance contract is on the
form
\[
I(\tilde{L}, \tilde{X}) = \begin{cases} 
0, & \tilde{L} \leq D, \\
\tilde{L} - D, & D < \tilde{L} \leq D + \bar{A}, \\
\bar{A}, & \tilde{L} > D + \bar{A}, 
\end{cases}
\]

for some unique \( D > 0 \). The optimal level of internal capital, \( A^* \), and corresponding deductible, \( D^* \), leads to a strictly positive probability of insurer default, \( D^* + A^* < 1 \).

Thus, the main results from the previous analysis naturally generalize to the case with multi-policy holders.

6 Concluding remarks

The introduction of costly internal capital leads to a rich set of implications in an otherwise standard insurance model. A natural future extension of our model would be to introduce multiple insurance lines, insured by the same insurance company. What is the optimal contract in such a setting, and how does this contract compare with the contracts seen in practice? How does diversification benefits affect the optimal level of internal capital in this case? These are important open questions, which we hope to address in future work.
Appendix

Proof of Proposition 1:

Form of optimal contract: We first show that any optimal contract must be on the form given in the Proposition. The general set of contracts, \( \mathcal{I} \) can be defined as the set of measurable compensation functions satisfying the constraints \( 0 \leq I(x) \leq \min(x, A) \). We define the subset of contracts \( \mathcal{I}_0 \subset \mathcal{I} \) that are piecewise continuous with a finite number of discontinuities, and note that this set is dense in \( \mathcal{I} \) under the \( L^1 \)-metric. Further, the operation \( I \mapsto Eu[-x + I(x) - P] \) is \( (L^1) \) continuous, so if there is an optimal contract in \( \mathcal{I}_0 \), this is also a globally optimal contract.

The variational problem within \( \mathcal{I}_0 \) is

\[
U = \max_{I(x) \in \mathcal{I}_0} \int_0^\infty u \left( -x + I(x) - \int_0^\infty I(y) \varphi(y) dy - \delta A \right) \varphi(x) dx,
\]

so that \( 0 \leq I(x) \leq \min(x, A) \). The first variation is

\[
\frac{\delta U}{\delta I} \bigg|_x = u' \left( -x + I(x) - \int_0^\infty I(y) \varphi(y) dy - \delta A \right) - \lambda.
\]

where \( \lambda = \int_0^\infty u'(-x + I(x) - P) dx \). The condition implies that there are three possibilities. First, that no constraints bind and the first variation is zero:

\[
u'(-1 + I(x) - P) = \lambda,
\]

second that the nonnegativity constraint binds, \( I(x) = 0 \), and the first variation is negative:

\[
u'(-1 + I(x) - P) < \lambda,
\]

third, that the upper constraint binds, \( I(x) = \min(x, A) \), and the first variation is positive

\[
u'(-1 + I(x) - P) > \lambda,
\]

and an identical argument as before implies that the optimal compact must be on the form

Since \( u' \) is strictly decreasing, the total position of the insuree, \(-x + I(x) - P\), under the first condition must be constant, i.e., \( I(x) = x - D \), for some \( D \geq 0 \). Further, if this position is feasible for \( x_1 \) and \( x_2 \) with \( x > 1 \), then it is also feasible for all \( x \in [x_1, x_2] \), so the region in which the contract takes this form must be an interval. Indeed, it must be the interval \([D, D + A]\), since a feasible improvement of the contract would otherwise be available at any point where the contract deviates from this form.

For \( x < D \), we are in the second case, and the nonnegativity constraint must be binding, so that \( I(x) = 0 \), and, finally, for \( x > D + A \), we are in the third case, so the upper constraint must be binding and \( I(x) = A \). Thus, any contract in \( \mathcal{I}_0 \) can be improved upon by choosing the stop-loss contract with some deductible, \( D \). We call the set of contracts on this form \( \mathcal{I}_1 \subset \mathcal{I}_0 \). Thus, if there is a uniquely optimal \( I \) in \( \mathcal{I}_1 \), then this is indeed the globally optimal contract in \( \mathcal{I} \).
Existence and uniqueness: Now, let us focus on contracts \( I \in \mathcal{I} \) and define \( F = Eu(-\bar{L} + I(\bar{L}) - P) \), which is obviously smooth as a function of \( D \). It follows that the partial derivative, \( \frac{\partial F}{\partial D} \), is given by

\[
\frac{\partial F}{\partial D} = Z\alpha - Z(1 - Z)u'(-D - P) + Z\beta,
\]

where

\[
P = A\Phi(D + A) - DZ + \int_{D}^{D+A} x\varphi(x)dx + \delta A,
\]

and

\[
Z = \Phi(D) - \Phi(D + A),
\]
\[
\alpha = \int_{D+A}^{\infty} u'(-x + A - P)\varphi(x)dx,
\]
\[
\beta = \int_{0}^{D} u'(-x - P)\varphi(x)dx.
\]

At \( D = 0 \), we have

\[
\frac{\partial F}{\partial D}\bigg|_{D=0} = (1 - \Phi(A))(\alpha - \Phi(A)u'(-P)) = (1 - \Phi(A))\left(\int_{A}^{\infty} u'(-x - P) - u'(-P)dx\right) > 0.
\]

Further, for large \( D \) we have

\[
\frac{\partial F}{\partial D} = Z(-u'(-D - P) + \int_{0}^{\infty} u'(-x - P)\varphi(x)dx + o(D)) < 0.
\]

Here \( o(D) \) is a higher order term, such that \( \lim_{D \to \infty} o(D) = 0 \). Thus, there must be at least one internal optimum, which will be characterized by the first order condition.

What remains is to prove uniqueness. Consider a \( D \), such that the first order condition is satisfied.
The second order condition at such a point is

\[
\frac{\partial^2 F}{\partial D^2} = \frac{\partial Z/\partial D}{Z} \times \frac{\partial F}{\partial D} + Z \left( (1 - Z)^2 u''(-D - P) - Z \left( \int_{D+\text{A}}^{\infty} u''(-x + A - D + \text{A}) \varphi(x) dx + \int_0^D u''(-x + D + \text{A}) \varphi(x) dx \right) \right)
\]

where we have used that \( \frac{\partial P}{\partial D} = -Z \), and \( Z > 0 \). Thus, any point where the first order condition is satisfied is a maximum, and consequently there is exactly one such point.

Continuity of \( D \) as a function of \( A \) follows from the smoothness of \( F \) as a function of \( D \) and \( A \), that \( \frac{\partial^2 F}{\partial D^2} < 0 \) at the optimum and the implicit function theorem. In fact, \( F \) is smooth enough to guarantee that \( D(A) \) is continuously differentiable, which we will use in the proof of Proposition 4. We are done.

**Proof of Proposition 2:**

For \( A \) close to zero, \( Z = A \varphi(D)(1 + O(A)) \), and \( P = O(A) \). Here, \( O(A) \) represents a function such that \( |O(A)| \leq CA \) for some constant \( C > 0 \).

The first order condition (10) can now be written

\[
\frac{\partial F}{\partial D} = Z\alpha - Z(1 - Z)u'(-D - P) + Z\beta = A\varphi(D)(1 + O(A)) \left( \int_D^{D+\text{A}} u'(-x) \varphi(x) dx - u'(-D) \right) + \int_0^D u'(-x) \varphi(x) dx + O(A)
\]

leading to

\[ u'(-D) = \mu + O(A). \]

The continuity and invertibility of \( u' \), and the strict negativity of \( u'' \), now implies the result.

**Proof of Proposition 3:**

From (2) and Proposition 1, it follows that

\[
P = \int_D^{D+\text{A}} (x - D) \varphi(x) dx + \int_0^{\infty} A\varphi(x) dx + \delta A \tag{11}
\]

\[
P = \int_D^{D+\text{A}} x \varphi(x) dx - D(\Phi(D) - \Phi(D + A)) + A\Phi(A + D) + \delta A \tag{12}
\]
and 1-3 follow immediately from this representation. Further, 4-7 follow from taking partial derivatives of first and second order of this expression.

Proof of Proposition 4: From Proposition 1, we know that any optimal contract must be a stop-loss contract with a deductible. Thus, if we can show that there is a unique \((A, D) \in \mathbb{R}^2_+\), among all such contracts that is optimal, we are done.

From the proposition, we know that for each possible \(A\), \(D(A)\) is unique. It also follows immediately from the costly internal capital, \(\delta A, \delta > 0\), that any optimal solution must have \(A^* \leq \bar{A}\), where \(u(-\delta \bar{A}) = Eu(-\bar{L})\). Thus, the maximal contract must lie in the compact set \(\{(A, D^*(A)) : 0 \leq A \leq \bar{A}\}\).

Since the objective function, \(F(A, D)\) belongs to \(C^2(\mathbb{R}^2_+)\), an interior optimal solution must necessarily satisfy the first order conditions (FOC) (5,6), but since the problem is not concave, it is a priori unclear that an interior optimum is unique. However, if it can be shown that at any point satisfying the FOC, the problem is locally concave in the sense that the Hessian,

\[
H = \begin{bmatrix}
\frac{\partial^2 F}{\partial A^2} & \frac{\partial^2 F}{\partial A \partial D} \\
\frac{\partial^2 F}{\partial D^2} & \frac{\partial^2 F}{\partial D^2}
\end{bmatrix}
\]

is strictly negative definite, then any interior optimum is indeed unique. Otherwise, the smooth function \(G(A) = F(A, D^*(A))\) would contain multiple maxima, without any local minimum, since \(0 = G'(A) = \frac{\partial F}{\partial A} + \frac{\partial F}{\partial D} dD^*\) can only occur at points where both FOC’s for \(F\) are satisfied \(\frac{\partial F}{\partial D} = 0\), as is then also \(\frac{\partial F}{\partial A}\) and they are always local maxima. Such a situation is of course impossible, and there can therefore only be — at most — one interior optimum.

Further, if there is an interior maximum, \((A^*, D(A^*))\), with \(A^* > 0\), then \(G\) is necessarily increasing for \(A < A^*\), so \((0, D(0))\) can not be a maximum. Similarly, if \((0, D)\) is a maximum, then \(G(A)\) is nonincreasing in a neighborhood of \(A = 0\). This can either occur if \(G'(0) < 0\), or if \(G'(0) = 0\), but in either case a similar argument as above implies that the no-insurance outcome is the unique maximum in this case. Thus, it is sufficient to prove that the Hessian is strictly negative definite at any point where the first order conditions are satisfied.

A second-order Taylor expansion of \(F\) at a point where \(\partial F/\partial A = 0\) yields:

\[
\begin{align*}
\frac{\partial^2 F}{\partial A^2} &= Q^2 \hat{c} + (Q - 1)^2 \hat{a} + ZQ^2 \hat{b}, \\
\frac{\partial^2 F}{\partial D^2} &= Z^2 \hat{c} + Z^2 \hat{a} + (Z - 1)^2 \hat{b}, \\
\frac{\partial^2 F}{\partial A \partial D} &= ZQ \hat{c} + Z(Q - 1) \hat{a} + (Z - 1)ZQ \hat{b},
\end{align*}
\]
where

\[
\hat{a} = \int_{D+A}^{\infty} u''(-x + A - P)\varphi(x)dx < 0,
\]
\[
\hat{b} = u''(-D - P) < 0,
\]
\[
\hat{c} = \int_{0}^{D} u''(x - P)\varphi(x)dx < 0,
\]
\[
Q = \delta + \Phi(D + A) > 0,
\]

and, as before, \( Z = \Phi(D) - \Phi(A + D) \).

By inspection, \( \frac{\partial^2 F}{\partial A^2} < 0 \) and \( \frac{\partial^2 F}{\partial D^2} < 0 \) (which we already proved in Proposition 2). Further,

\[
det[H] = \left( \frac{\partial^2 F}{\partial A^2} \right)^2 - \left( \frac{\partial^2 F}{\partial A \partial D} \right)^2 = Z(\hat{b}\hat{c}Q^2 + \hat{a}\hat{c}Z + \hat{a}\hat{b}(Q + Z - 1)^2) > 0,
\]

and together this implies that \( H \) is indeed strictly negative definite. Thus, the result follows.

**Proof of Proposition 5**: Sufficiency: We calculate \( \frac{\partial F}{\partial A} \) at \( D = \bar{D}, A = 0 \),

\[
\frac{\partial F}{\partial A} \bigg|_{A=0,D=\bar{D}} = \alpha - (\delta + \Phi(D + A))(\alpha + Z\mu'(-D - P) + \beta),
\]

\[
= \int_{D}^{\infty} u'(-x)\varphi(x)dx - (\delta + \Phi(D))\mu'(-\bar{D})
\]

\[
= \int_{D}^{\infty} (u'(-x) - \mu w')\varphi(x)dx - \delta\mu'(-\bar{D})
\]

\[
= \int_{D}^{\infty} |u'(-x) - \mu w'|\varphi(x)dx - \delta\mu'\tag{13}
\]

Now, from (4), we have

\[
0 = \int_{0}^{D} (u'(-x) - \mu w')\varphi(x)dx
\]

\[
= \int_{D}^{\infty} (u'(-x) - \mu w')\varphi(x)dx + \int_{0}^{\bar{D}} (u'(-x) - \mu w')\varphi(x)dx,
\]

\[
= \int_{D}^{\infty} |u'(-x) - \mu w'|\varphi(x)dx - \int_{0}^{\bar{D}} |u'(-x) - \mu w'|\varphi(x)dx,
\]

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implying that

\[ E[|u'(-\tilde{L}) - \mu_w'|| = \int_D^\infty |u'(-x) - \mu_w'| \varphi(x)dx + \int_0^D |u'(-x) - \mu_w'| \varphi(x)dx \]

\[ = 2 \int_D^\infty |u'(-x) - \mu_w'| \varphi(x)dx. \]

Plugging this into (13) yields

\[ \frac{\partial F}{\partial A} \bigg|_{A=0,D=\bar{D}} = \frac{1}{2} E[|u'(-\tilde{L}) - \mu_w'|] - \delta \mu_w', \quad (14) \]

and if this is positive, a small amount of insurance is indeed better than no insurance, so insurance is optimal.

Necessity: Now, assume that \( \frac{1}{2} E[|u'(-\tilde{L}) - \mu_w'|] < \delta \mu_w' \). We use a similar argument as in the proof of Proposition 4. First, note that \( \frac{\partial F}{\partial D} \bigg|_{A=0} = 0 \). A Taylor expansion of \( G(A) \) in a neighborhood of \( A = 0 \) yields

\[ G(\Delta A) = \frac{\partial F}{\partial A} \Delta A + \frac{\partial F}{\partial D} D' (0) \Delta A + o(\Delta A) = \left( \frac{1}{2} E[|u'(-\tilde{L}) - \mu_w'|] - \delta \mu_w' \right) \Delta A + o(\Delta A) < 0. \]

A similar argument as in the proof of Proposition 4 implies that \( G \) is decreasing for all \( A \), and thus that no insurance is the optimal solution. We are done.

\[ \begin{aligned} \text{Proof of Proposition 6:} \quad & \delta \geq 1: \text{It is trivial that insurance is always suboptimal in this case: Any insurance contract with } A > 0 \text{ will lead to strictly first order stochastically dominated payoffs compared with no insurance, since the price for insurance is at least as high as what can ever be claimed, and in some states higher.} \\ & \delta < 1: \text{The result follows almost immediately from the following Lemma.} \\ \text{Lemma:} & \sup E[|\tilde{Z} - \mu_Z|] = 2, \text{ where the supremum is taken over all nonnegative random variables with infinitely differentiable probability distribution functions.} \\ \text{Proof:} & \text{From the triangle inequality it follows that } E[|\tilde{Z} - \mu_Z|] \leq E[|\tilde{Z}|] + \mu_Z = 2\mu_Z, \text{ so } 2 \text{ is an upper bound. Now, let } \tilde{Z} \text{ have a two-point distribution with probability } 1 - \epsilon \text{ that } \tilde{Z} = 0 \text{ and probability } \epsilon \text{ that } \tilde{Z} = \bar{Z}, \bar{Z} > 0. \text{ Then } \mu_Z = \bar{Z}, \text{ and } E[|\tilde{Z} - \mu_Z|] = (1 - \epsilon)\mu_Z + \epsilon (\bar{Z} - \mu_Z) = 2(1 - \epsilon)\mu_Z. \text{ Thus, by choosing } \epsilon \text{ arbitrarily close to zero, one can get arbitrarily close to the upper bound. The only technicality is that the distribution is not smooth. However, since the infinitely differentiable distribution functions form a dense subset of the set of distribution functions, and the operations involved are continuous, the supremum is } 2 \text{ also for this subset.} \]

Now, given the risk \( \tilde{L} \) with density function \( \varphi \), it is clear that a smooth increasing function \( u' \) can be chosen so that the distribution of \( Z \equiv u'(-\tilde{L}) \) is arbitrarily close to the sequence of two point distributions in the lemma, i.e., such that \( E[|u'(-\tilde{L}) - \mu_w'|] \geq 2(1 - \epsilon)\mu_w', \text{ for arbitrary } \epsilon > 0. \) But
when plugging this into (14), it then follows that

\[
\left. \frac{\partial F}{\partial A} \right|_{A=0,D=\bar{D}} = \frac{1}{2} E[|u'(\tilde{L}) - \mu_{u'}|] - \delta \mu_{u'} \geq \left( \frac{1}{2} 2(1 - \epsilon) - \delta \right) \mu_{u'} > 0,
\]

for small enough \( \epsilon \), so the risk is indeed insurable.

Proof of Proposition 7: It is clear that it can never be optimal to choose the deductible and internal capital such that \( D + A > \bar{L} \), since by choosing \( A = \bar{L} - D \) the contract makes the same payments in all states but the premium is lower. Thus, it is sufficient to focus on contracts such that \( D + A = \bar{L} \).

Now, assume that the optimal deductible and internal capital is such that \( D^* + A^* = \bar{L} \). The first order condition with respect to the deductible is in this case:

\[
\frac{\partial F}{\partial D} = -\Phi(D) \left( 1 - \Phi(D) \right) u'(-D - P) - \int_0^D u'(-x - P) \varphi(x) dx < 0.
\]

Thus, a better contract can be constructed by decreasing the deductible, leading to a contradiction, and therefore no optimal contract can have \( D + A \geq \bar{L} \).

Proof of Proposition 8: Taking the differential of

\[
\begin{pmatrix}
\frac{\partial F}{\partial A} \\
\frac{\partial F}{\partial D}
\end{pmatrix}
\]

around \( A^* \), \( D^* \), \( \delta \) yields

\[
\begin{pmatrix}
\frac{\partial F}{\partial A} \\
\frac{\partial F}{\partial D}
\end{pmatrix}
\bigg|_{A^* + dA,D^*+dD,\delta+d\delta} - \begin{pmatrix}
\frac{\partial F}{\partial A} \\
\frac{\partial F}{\partial D}
\end{pmatrix}
\bigg|_{A^*,D^*,\delta} = H \begin{pmatrix}
dA \\
dD
\end{pmatrix} + \begin{pmatrix}
\frac{\partial^2 F}{\partial A^2} \\
\frac{\partial^2 F}{\partial D^2}
\end{pmatrix} d\delta,
\]

where \( H \) is the Hessian matrix defined in Proposition 4.

To keep the FOC, the differential must be zero, so

\[
\begin{pmatrix}
dA \\
dD
\end{pmatrix} = -H^{-1} \begin{pmatrix}
\frac{\partial^2 F}{\partial A^2} \\
\frac{\partial^2 F}{\partial D^2}
\end{pmatrix} d\delta.
\]
Using the fact that \( H \) is negative definite at the optimum, implying that \( \det[H] > 0 \), calculating
\[
\frac{\partial^2 F}{\partial A \partial b} = -u'(-D - P) + A(Q\tilde{c} + (Q - 1)\tilde{a} + Q\tilde{b}),
\]
\[
\frac{\partial^2 F}{\partial D \partial b} + AZ(\tilde{c} + \tilde{a} + (Z - 1)\tilde{b}),
\]
and plugging in the elements of \( H \), we get
\[
dA \overline{\delta} = -\frac{1}{\det[H]} \left( \frac{\partial^2 F}{\partial D^2} \times \frac{\partial^2 F}{\partial A \partial \delta} - \frac{\partial^2 F}{\partial D \partial A} \times \frac{\partial^2 F}{\partial D \partial \delta} \right)
\]
\[
= -\frac{Z}{\det[H]} \left( \hat{b}^2 Q(1 - Z)^3 + \hat{b}cQ(1 + Z - Z^2) + \hat{a}b((Z + Q - 1) + QZ(1 - Z)) + u'(D + P) \left( \frac{\partial^2 F}{\partial D^2} \right) \right).
\]
Here, all terms are defined as in the proof of Proposition 4.

We note that all terms within the parentheses are immediately strictly positive, except for \( Z + Q\tilde{c} + (Q - 1)\tilde{a} + Q\tilde{b} \). Also, since \( b \), which, when the function is strictly concave, must lie in \([0, L]\), the proposition, this term is also weakly positive, so the expression within the parentheses is positive, and \( \frac{dA}{\overline{\delta}} \) is therefore strictly positive.

**Proof of Proposition 9.** 1 and 2. Clearly, since \( \delta > 0 \), choosing \( A = \bar{L} \) always dominates choosing \( A > \bar{L} \), as the insurance payoffs are identical in both states of the world, but the cost of internal capital is higher if \( A > \bar{L} \) than if \( A = \bar{L} \). Thus, the solution, which is unique, since the objective function is strictly concave, must lie in \([0, \bar{L}]\). Further, it is clear that if \( \delta + p \geq 1 \), then \( A^* = 0 \) since self-insurance is optimal in this case. The results are trivial in this case and we therefore proceed with the case when \( \delta + p < 1 \).

Define \( q = \delta + p \). The first order condition from (5) is
\[
(1 - p)qu'(-qA^*) = p(1 - q)u'((1 - q)A^* - \bar{L}),
\]
which, when the function \( b_{\bar{L}}(A) \overset{\text{def}}{=} \frac{u'(-qA)}{u'((1 - q)A - \bar{L})} \) is defined is equivalent to
\[
b_{\bar{L}}(A^*) = \frac{p}{1 - p} \times \frac{1 - q}{q}, \tag{15}
\]
where, since \( q > p \), the right hand side is strictly less than 1. Now, since \( u \) is strictly concave and twice continuously differentiable, it follows that \( b_{\bar{L}}(A) \) is strictly increasing in \( A \). Also, \( b_{\bar{L}}(0) = \frac{u'(-\bar{L})}{u'((1 - q)\bar{L} - \bar{L})} \), and if \( b_{\bar{L}}(0) \leq \frac{p}{1 - p} \times \frac{1 - q}{q} \), it must then be that \( A^* = 0 \), which immediately implies 2. Also, since \( b_{\bar{L}}(\bar{L}) = 1 > \frac{p}{1 - p} \times \frac{1 - q}{q} \), the maximum must indeed be realized for \( A^* < \bar{L} \), so 1 follows.

We also note that the monotonicity of the utility function, \( u \), obviously implies that \( b_{\bar{L}} \) is positive.

3. Define \( V = b_{\bar{L}} - \frac{p}{1 - p} \times \frac{1 - q}{q} \). Then, the first order condition is \( V(A^*, \bar{L}) = 0 \). A Taylor expansion
around \((A^*, \bar{L})\) yields \(dV = \frac{\partial V}{\partial A^*} dA^* + \frac{\partial V}{\partial \bar{L}} d\bar{L}\). From the previous argument, we know that \(\frac{\partial V}{\partial A^*} = b'_{\bar{L}} > 0\). So, it is sufficient to show that \(\frac{\partial V}{\partial \bar{L}} < 0\) for the result to follow, since

\[
\frac{dA^*}{dV} = -\frac{\partial V}{\partial \bar{L}}.
\]

Differentiating \(V\) with respect to \(\bar{L}\) leads to

\[
\frac{\partial V}{\partial \bar{L}} = -ARA((1 - q)A - \bar{L})b_{\bar{L}} < 0,
\]

and the result follows.

4. and 5. We have \(P_Q(A) = p(\bar{L} - A)\) for \(A < \bar{L}\). Therefore, \(\frac{dP_Q}{dL} = p \left(1 - \frac{dA^*}{dL}\right)\). So, if \(\frac{dA^*}{dL} < 1\), then \(\frac{dP_Q}{dL} > 0\).

From the proof of 3., it follows that

\[
\frac{dA^*}{dL} = \frac{\frac{\partial b_{\bar{L}}}{\partial A^*}}{\frac{\partial b_{\bar{L}}}{\partial \bar{A}}} = \frac{ARA((1 - q)A - \bar{L})b_{\bar{L}}}{(qARA(-qA) + (1 - q)ARA((1 - q)A - \bar{L})\bar{b}_{\bar{L}}) = \frac{ARA((1 - q)A - \bar{L})}{qARA(-qA) + (1 - q)ARA((1 - q)A - \bar{L})}.
\]

Now, since \((1 - q)A - \bar{L} < -qA\), and for an agent with DARA preferences \(ARA\) is positive and decreasing, \(\frac{dA^*}{dL}\) is therefore less than 1, and 4. follows. A similar argument for IARA preferences leads to 5.

6. Given that \(V = b_{\bar{L}} - \frac{p}{1 - p} - \frac{1 - q}{q}\). Then, the first order condition is \(V(A^*, \delta) = 0\). A Taylor expansion around \((A^*, \delta)\) yields \(dV = \frac{\partial V}{\partial A^*} dA^* + \frac{\partial V}{\partial \delta} d\delta\). From the previous argument, we know that \(\frac{\partial V}{\partial A^*} = b'_{\bar{L}} > 0\), and we get

\[
\frac{\partial V}{\partial \delta} = \frac{p}{1 - p} + A^* \times ARA((1 - q)A^* - \bar{L}) \times \frac{u'(-A^* q)}{u'((1 - q)A^* - \bar{L})} - A^* \times ARA(-qA^*) \times \frac{u'(-A^* q)}{u'((1 - q)A^* - \bar{L})}
\]

\[
= \frac{p}{1 - p} \frac{1}{q^2} + A^* \frac{p}{p - q} - (ARA((1 - q)A^* - \bar{L}) - ARA(-qA^*))
\]

\[
= \frac{p}{1 - p} \frac{1}{q^2} (1 + A^* q(1 - q)(ARA((1 - q)A^* - \bar{L}) - ARA(-qA^*))).
\]

For comparative static purposes, we set \(dV = 0\), to get \(\frac{dA^*}{d\delta} = -\frac{\partial V}{\partial \bar{L}}\) and the condition in 6. is then indeed necessary and sufficient for \(\frac{dA^*}{d\delta} < 0\). We are done.

\[\]

The case with many risks (Section 5): Consider the continuous strictly positive probability density function \(\varphi\), with support on \([0, 1]\), and define \(p = \int_0^1 \varphi(x) dx\). For a given \(N\), define the \(N\) numbers,
\[ \phi_n^N = N \int_{(n-1)/N}^{n/N} \varphi(x)dx, \text{ and the total probability for } n \text{ realized losses when there are } N \text{ risks, as} \]
\[ p_n^N = \frac{1}{N} \varphi_n^N. \]

Since all risks are symmetric, the probability for a specific (ordered) combination of outcomes, \((\tilde{L}_1, \tilde{L}_2, \ldots, \tilde{L}_N)\), for which there are \(n\) realized losses is then
\[ q_n^N = \left( \frac{N}{n} \right)^{-1} \phi_n^N, \]

Via Stirling’s approximation formula, it follows that an asymptotically equivalent definition of the probability for a specific realization of losses, \((\tilde{L}_1, \tilde{L}_2, \ldots, \tilde{L}_N)\), for which there are in total \(n\) realized losses, is the following:
\[ \bar{q}_n^N = \sqrt{2 \pi \frac{z}{N}} \frac{z^{n+1/2} (1-z)^{(N-n)+1/2}}{\phi_n^N b_n^N}. \]

Here, \(z = \frac{n}{N}\). The corresponding probability of this loss realization if the risks instead have a standard binomial distribution with probability \(z\), \(\text{Bin}(n, z)\), is
\[ b_n^N = z^n (1-z)^{N-n}, \]

so equivalently we can write
\[ \bar{q}_n^N = \sqrt{2 \pi \frac{z}{N}} \sqrt{\frac{1}{z} z^N b_n^N}. \]

Thus, the probabilities can be viewed as modified compared with the standard binomial distribution (which is based on independent risks), in a way such that any aggregate loss distribution can be obtained.

It is straightforward to check that the unconditional expectation is indeed \(E[\tilde{L}_i] = p\), for all \(N\), and that asymptotic joint moments of all orders \(E \left[ \prod_{k=1}^{K} (\tilde{L}_{m_k})^{n_k} \right] \), exist as \(N \to \infty\), for arbitrary finite sequences \(n_1, \ldots, n_K, m_1, \ldots, m_K, K > 1\). Moreover, it is also easy to check that asymptotically, the conditional distributions of \(\tilde{X}\) given \(\tilde{L}_i = 0\) and \(\tilde{L}_i = 1\), are the same as the unconditional probabilities. Thus, this construction method provides a formal justification using discrete individual risks and absolutely continuous nondegenerate total loss distribution.

**Proof of Proposition 10:**

The proof is very similar to the proofs of Propositions 1 and 7. We provide a sketch: The variational problem within \(\mathcal{L}_0\) is
\[ U = \max_I \int_0^1 u\left( -1 + I(1,x) - \int_0^1 I(1,y) \varphi(y)dy - \delta A \right) \varphi(x)dx + (1-p)u\left( I(0,x) - \int_0^1 I(1,y) \varphi(y)dy - \delta A \right), \]

so that \(0 \leq I(x) \leq \min(\tilde{L}_i, \tilde{A})\). Obviously, the only feasible constraint in case of no losses is \(I(0,x) = 0\), so we focus on \(I(1,x) \equiv I(x)\). The first variation is
\[ \frac{\delta U}{\delta I} \bigg|_x = u' \left( -1 + I(x) - \int_0^1 I(y) \varphi(y)dy - \delta A \right) - \lambda. \]

where \(\lambda = \int_0^\infty u'(-1 + I(x) - P)dx + \frac{1-p}{P} u(-P)\), where \(P = \int_0^1 I(y) \varphi(y)dy + \delta A\). As before, the
condition implies the three possibilities:

\[ u'(-x + I(x) - P) = \lambda, \]

second that the nonnegativity constraint binds, \( I(x) = 0 \), and the first variation is negative:

\[ u'(-x + I(x) - P) < \lambda, \]

third, that the upper constraint binds, \( I(x) = \min(x, \bar{A}) \), and the first variation is positive

\[ u'(-x + I(x) - P) > \lambda, \]

through an identical argument as before leading to the optimal contract

\[
I(\tilde{L}, \tilde{X}) = \begin{cases} 
0, & \tilde{L} \leq D, \\
\tilde{L} - D, & D < \tilde{L} \leq D + \bar{A}, \\
\bar{A}, & \tilde{L} > D + \bar{A},
\end{cases}
\]

for some \( 0 \leq D \leq 1 - \bar{A} \). It is straightforward to check—using an identical argument as before—that

\[
\frac{dU}{dD}\bigg|_{D=0} > 0, \quad \frac{dU}{dD}\bigg|_{D=1-A} < 0, \quad \text{and} \quad \frac{d^2U}{dD^2} < 0 \quad \text{for} \quad 0 \leq D \leq 1 - \bar{A},
\]

so given \( A > 0 \), there is a unique optimal deductible, \( 0 < D < 1 - \bar{A} \).

Finally, it is straightforward to check that \( \frac{dU}{dA}\bigg|_{A=1} = -\delta A < 0 \), so any optimal level of internal capital, \( A^* < 1 \), and corresponding deductible \( 0 < D^* < 1 - A^* \) must have a strictly positive risk of insurer default.
References


