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First Impressions Matter:
A Model of Confirmatory Bias

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Abstract 

Psychological research indicates that people have a cognitive bias that leads them to misinterpret new information as supporting previously held hypotheses. We model such confirmatory bias in a symmetric model in which exactly one of two hypotheses is true. We show that the confirmatory bias induces overconfidence: Given any probabilistic assessment by an agent that one of the hypotheses is probably true, the appropriate beliefs should deem it less likely to be true. When the agent believes relatively weakly in a hypothesis after receiving extensive information, the hypothesis he believes in may be more likely to be wrong than right. If the confirmatory bias is strong enough, with positive probability the agent may eventually come to believe with near certainty in a false hypothesis even after receiving an infinite amount of information.

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The human understanding when it has once adopted an opinion draws all things else to support and agree with it. And though there be a greater number and weight of instances to be found on the other side, yet these it either neglects and despises, or else by some distinction sets aside and rejects, in order that by this great and pernicious predetermination the authority of its former conclusion may remain inviolate.

— Francis Bacon

1. Introduction

How do people form beliefs in situations of uncertainty? Economists have traditionally assumed that people begin with subjective beliefs over the different possible states of the world, and use Bayes’ Rule to update those beliefs. This elegant and powerful model of economic agents as Bayesian statisticians is the foundation of modern information economics.

Yet a large and growing body of psychological research suggests that the way people process information often departs systematically from Bayesian updating. In this paper, we formally model and explore the consequences of one particular departure from Bayesian rationality, confirmatory bias. A person suffers from confirmatory bias if he tends to misinterpret ambiguous evidence as confirming his current hypotheses about the world. Teachers misread performance of pupils as supporting their initial impressions of those pupils; many people misread their observations of individual behavior as supporting their prior stereotypes about groups to which these individuals belong; scientists biasedly interpret data as supporting their hypotheses.

Our simple model by and large confirms an intuition common in the psychology literature: Confirmatory bias leads to overconfidence, in the sense that people on average believe more strongly than they should in their favored hypotheses. The model also yields surprising further results. An agent who suffers from confirmatory bias may come to believe in a hypothesis that is probably wrong, meaning that a Bayesian observer who was aware of the agent’s confirmatory bias would, after observing the agent’s beliefs, favor a different hypothesis than the agent. We also show that even an infinite amount of information does not necessarily overcome the effects of confirmatory bias. Over time an agent may with positive probability come to believe with near certainty in the wrong hypothesis.

In Section 2—which readers impatient for math may wish to skip—we review some of the psychological evidence that humans are prone to confirmatory bias. In Section 3 we present our formal model, and provide examples and general propositions illustrating the implications of confirmatory bias.

1 From The New Organon and Related Writings (1960; 1620), quoted in Nisbett and Ross (1980, p. 167).
We consider a situation where an agent initially believes that each of two possible states of the world is equally likely. The agent then receives a series of independent and identically distributed signals that are correlated with the true state. To model confirmatory bias, we assume that when the agent gets a signal that is counter to the hypothesis he currently believes is more likely, there is a positive probability that he misreads that signal as supporting his current hypothesis. Because we assume that the agent always recognizes evidence that confirms his current beliefs, relative to proper Bayesian updating he is biased towards confirming his current hypothesis.

So, for example, a teacher may believe either that Marta is smarter than Bart or that Bart is smarter than Marta; he initially believes each is equally likely, and over time he collects a series of signals that help him to identify who is smarter. If, after receiving one or more signals, the teacher believes that Marta is probably smarter than Bart, confirmatory bias may lead him to erroneously interpret his next signal as supporting this hypothesis. Therefore, the teacher’s updated belief that Marta is smarter than Bart may be stronger than is warranted.

The notion that the teacher is likely to believe “too strongly” that Marta is smarter corresponds to the commonly-held intuition that confirmatory bias leads to overconfidence. While qualifying this intuition with several caveats, our model by and large confirms it: Given any probabilistic assessment by an agent that one of the hypotheses is probably true, the appropriate beliefs should on average deem it less likely to be true. Intuitively, a person who believes strongly in a hypothesis is likely to have misinterpreted some signals that conflict with what he believes, and hence is likely to have received more evidence against his believed hypothesis than he realizes.

Our analysis shows that a more surprising result arises when confirmatory bias is severe: A Bayesian observer with no direct information of her own, but who can observe the agent’s belief in favor of one hypothesis, may herself believe that the other hypothesis is more likely. We show that such “wrongness” can arise when the agent’s evidence is sufficiently mixed. Intuitively, if the agent has perceived almost as much evidence against his hypothesis as supporting it, then, since some of the evidence he perceives as supportive is actually not supportive, it is likely that a majority of the real signals oppose his hypothesis. Because such wrongness only arises when the agent has relatively weak evidence supporting his favored hypothesis, however, the agent on average correctly judges which of the two hypotheses is more likely, in the sense that his best guess is right most of the time.

While seemingly straightforward, the intuition for our overconfidence and wrongness results conceals some subtle implications of the agent’s confirmatory bias. For example, an agent who currently believes in Hypothesis A (say) may have once believed in Hypothesis B, at which time he had a propensity to misread evidence in favor of Hypothesis A. But then the agent may underestimate how many signals supporting Hypothesis A he has received, and thus he may be underconfident in his belief in favor of Hypothesis A. Indeed, we show that an agent who has only recently come to believe in a hypothesis is likely to be underconfident in that hypothesis, because until recently he has been biased against his current
hypothesis. If a teacher used to think Bart was smarter than Marta and only recently concluded that Marta is smarter, then probably he has been ignoring evidence all along that Marta is smarter. The simple overconfidence and wrongness results hold because an agent has probably believed in his currently held hypothesis during most of the time he has been receiving information and so, on average, has been biased towards this hypothesis.

In Section 4 we investigate the implications of confirmatory bias after the agent receives an infinite sequence of signals. In the absence of confirmatory bias, an agent will always come to believe with near certainty in the correct hypothesis if he receives an infinite sequence of signals. If the confirmatory bias is sufficiently severe or the strength of individual signals is weak, however, then with positive probability the agent may come to believe with near certainty that the incorrect hypothesis is true. Intuitively, once the agent comes to believe in an incorrect hypothesis, the confirmatory bias inhibits his ability to overturn his erroneous beliefs. If the bias is strong enough, the expected drift once the agent comes to believe in the false hypothesis is towards believing more strongly in that hypothesis, guaranteeing a positive probability that the agent ends up believing very strongly in the false hypothesis. The results of Section 4 belied the common intuition that learning will eventually correct cognitive biases. While this is true for sufficiently mild confirmatory bias, when the bias is sufficiently severe “learning” can exacerbate the bias.

The premise of this paper is that explicit formalizations of departures from Bayesian information processing are crucial to incorporating psychological biases into economic analysis. We do not in this paper take the important next step of developing specific economic applications of the bias we model. We conclude in Section 5, however, by discussing some possible implications of our model in multi-person economic situations, as well as highlighting some likely problems with such applications.

2. A Review of the Psychology Literature

Many different strands of psychological research yield evidence on phenomena that we are modeling under the rubric of confirmatory bias. Before reviewing this literature, we first wish to distinguish a form of “quasi-Bayesian” information processing from the bias we are examining. Though the two phenomena are related—and not always distinguished clearly in the psychology literature—they differ importantly in their implications for decision theory. Suppose that, once they form a strong hypothesis, people simply stop being attentive to relevant new information that contradicts or supports their hypotheses. Intuitively, when you become convinced that one investment strategy is more lucrative than another, you may simply stop paying attention to even freely available additional information.²

² Such behavior corresponds to a natural economic “cognitive-search” model: If we posit a cost to information processing, in many settings the natural stopping rule would be to process information until beliefs are sufficiently strong in one direction or another, then stop.
Bruner and Potter (1964) elegantly demonstrate such anchoring. About 90 subjects were shown blurred pictures that were gradually brought into sharper focus. Different subjects began viewing the pictures at different points in the focusing process, but the pace of the focusing process and final degree of focus were identical for all subjects. Strikingly, of those subjects who began their viewing at a severe-blur stage, less than a quarter eventually identified the pictures correctly, whereas over half of those who began viewing at a light-blur stage were able to correctly identify the pictures. Bruner and Potter (1964, p. 424) conclude that “Interference may be accounted for partly by the difficulty of rejecting incorrect hypotheses based on substandard cues.” That is, people who use weak evidence to form initial hypotheses have difficulty correctly interpreting subsequent, better information that contradicts those initial hypotheses.3

This form of anchoring does not necessarily imply that people misinterpret additional evidence to either disconfirm or confirm initial hypotheses, only that they ignore additional evidence. Such a tendency to anchor on initial hypotheses can therefore be reconciled with Bayesian information processing. While such anchoring is potentially quite important, psychological evidence reveals a stronger and more provocative phenomenon: People tend to misread evidence as additional support for initial hypotheses. If a teacher initially believes that one student is smarter than another, she has the propensity to confirm that hypothesis when interpreting later performance.4 Lord, Ross, and Lepper (1979, p. 2099) posited some of the underlying cognitive mechanisms involved in such propensities:

...there is considerable evidence that people tend to interpret subsequent evidence so as to maintain their initial beliefs. The biased assimilation processes underlying this effect may include a propensity to remember the strengths of confirming evidence but the weaknesses of disconfirming evidence, to judge confirming evidence as relevant and reliable but disconfirming evidence as irrelevant and unreliable, and to accept confirming evidence at face value while scrutinizing disconfirming evidence hypercritically. With confirming evidence, we suspect that both lay and professional scientists rapidly reduce the complexity of the information and remember only a few well-chosen supportive impressions. With disconfirming evidence, they continue to reflect upon any information that suggests less damaging “alternative interpretations.” Indeed, they may even come to regard the ambiguities and conceptual flaws in the data opposing their hypotheses as somehow suggestive of the fundamental correctness of

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3 A similar experiment (Wyatt and Campbell (1951)) was cited by Perkins (1981) as one interpretation of the perspective that “fresh” thinkers may be better at seeing solutions to problems than people who have meditated at length on the problems, because the fresh thinkers are not overwhelmed by the “interference” of old hypotheses.

4 A related arena where the confirmation bias has been studied widely is in counselor judgments: Counselors in clinical settings tend to confirm original suppositions in their eventual judgments. If you are told ahead of time that an interviewee is combative, then both your conduct and your interpretation of his conduct during an interview may reinforce that supposition, even if he is in fact no more combative than the average person. See, e.g., Haverkamp (1993). There has also been extensive research on confirmatory bias in the interviewing process more generally; see, e.g., Dougherty, Turban, and Callender (1994) and Macan and Dipboye (1994). Research applying variants of confirmatory bias to other domains includes Arkes (1989) and Borum, Otto, and Golding (1993) to the law; Baumann, Debor, and Thompson (1991) to medicine; and Souter (1993) discusses the implications of overconfidence to business insurance.
those hypotheses. Thus, completely inconsistent or even random data – when “processed” in a suitably biased fashion – can maintain or even reinforce one’s preconceptions.

The most striking evidence for the confirmatory bias is a series of experiments demonstrating how providing the same ambiguous information to people who differ in their initial beliefs on some topic can move their beliefs further apart. To illustrate such polarization, Lord, Ross, and Lepper (1979) asked 151 undergraduates to complete a questionnaire that included three questions on capital punishment. Later, 48 of these students were recruited to participate in another experiment. Twenty-four of them were selected because their answers to the earlier questionnaire indicated that they were “proponents” who favored capital punishment, believed it to have a deterrent effect, and thought most of the relevant research supported their own beliefs. Twenty-four were opponents who opposed capital punishment, doubted its deterrent effect and thought that the relevant research supported their views.” These subjects were then asked to judge the merits of randomly selected studies on the deterrent efficacy of the death penalty, and to state whether a given study (along with criticisms of that study) provided evidence for or against the deterrence hypothesis. Subjects were then asked to rate, on 16 point scales ranging from -8 to +8, how the studies they had read moved their attitudes towards the death penalty, and how they had changed their beliefs regarding its deterrent efficacy. Lord, Ross, and Lepper (1979, pp. 2102-4) summarize the basic results (all of which hold with confidence p < .01) as follows:

The relevant data provide strong support for the polarization hypothesis. Asked for their final attitudes relative to the experiment’s start, proponents reported that they were more in favor of capital punishment, whereas opponents reported that they were less in favor of capital punishment ... Similar results characterized subjects’ beliefs about deterrent efficacy. Proponents reported greater belief in the deterrent effect of capital punishment, whereas opponents reported less belief in this deterrent effect.

Plous (1991) replicates the Lord, Ross, Lepper results in the context of judgments about the safety of nuclear technology. Pro- and anti-nuclear subjects were given identical information and arguments regarding the Three Mile Island nuclear disaster and a case of false military alert that could have lead to the launching of U.S. nuclear missiles. Plous (1991, p. 1068) found that 54% of pro-nuclear subjects became more pro-nuclear from the information, while only 7% became less pro-nuclear. By contrast, only 7% of the anti-nuclear subjects became less anti-nuclear from the information while 45% became more anti-nuclear.⁵

⁵ These percentages were derived from Table 2 of Plous (1991, p. 1068), aggregating across two studies; the remaining subjects in each case reported no change in beliefs. For other papers following on Lord, Ross, and Lepper (1979), see Fleming and Arrowood (1979), Jennings, Lepper, and Ross (1981), Hubbard (1984), Lepper, Ross, and Lau (1986); see also Miller, McHoskey, Bane, and Dowd (1993) for more mixed evidence regarding the Lord, Ross, and Lepper experiment. In the passage above, Lord, Ross, and Lepper posit that even professional scientists are susceptible to such same-evidence polarization. Indeed,
Darley and Gross (1983) demonstrate a related and similarly striking form of polarization due to confirmatory bias. Seventy undergraduates were asked to assess a nine-year-old girl’s academic skills in several different academic areas. Before completing this task, the students received information about the girl and her family and viewed a video tape of the girl playing in a playground. One group of subjects was given a fact sheet that described the girl’s parents as college graduates who held white-collar jobs; these students viewed a video of the girl playing in what appeared to be a well-to-do, middle class neighborhood. The other group of subjects was given a fact sheet that described the girl’s parents as high school graduates who held blue-collar jobs; these students viewed a video of the same girl playing in what appeared to be an impoverished inner-city neighborhood. Half of each group of subjects were then asked to evaluate the girl’s reading level, measured in terms of equivalent grade level. There was a small difference in the two groups’ estimates—those subjects who had viewed the “inner-city” video rated the girl’s skill level at an average of 3.90 (i.e., 9/10 through 3rd grade) while those who had viewed the “suburban video” rated the girl’s skill level at an average of 4.29. The remaining subjects in each group were shown a second video of the girl answering (with mixed success) a series of questions. Afterwards, they were asked to evaluate the girl’s reading level. The inner-city video group rated the girl’s skill level at an average of 3.71, significantly below the 3.90 estimate of the inner-city subjects who did not view the question-answer video. Meanwhile, the suburban video group rated the girl’s skill level at an average of 4.67, significantly above the 4.29 estimate of the suburban subjects who did not view the second video. Even though the two groups viewed the identical question-and-answer video, the additional information further polarized their assessments of the girl’s skill level. Darley and Gross (1983) interpret this result as evidence of confirmatory bias—subjects were influenced by the girl’s background in their initial judgments, but their beliefs were evidently influenced even more strongly by the effect their initial hypotheses had on their interpretation of further evidence.

Our reading of the psychology literature leads us to conclude that any of three different information processing problems contribute to confirmatory bias. First, researchers widely recognize that confirmatory bias and overconfidence arise when people must interpret ambiguous evidence (sec., e.g., Keren (1987) and Griffin and Tversky (1992)). Lord, Ross, and Lepper’s (1979) study, discussed above, clearly

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6 The subjects were also asked to evaluate the girl’s mathematics and liberal arts skill levels; we report the results that are least supportive of the existence of confirmatory bias.
illustrates the point. Keren (1988) notes the lack of confirmatory bias in visual perceptions and concludes that confirmatory tendency depends on some degree of abstraction and “discrimination” (i.e., the need for interpretation) not present in simple visual tasks. A primary mechanism of stereotype-maintenance is our tendency to interpret ambiguous behavior according to previous stereotype. Similarly, a teacher may interpret an ambiguous answer by a student as either creative or just plain stupid, according to his earlier impressions of the student, but will be less likely to biasedly interpret more objective feedback such as answers to multiple-choice questions.

Second, confirmatory bias can arise when people must interpret statistical evidence to assess the correlation between phenomena that are separated by time. Nisbett and Ross (1980) argue that the inability to accurately identify such correlation (e.g., between hyperactivity and sugar intake, or between performance on exams and the time of day the exams are held) is one of the most robust shortcomings in human reasoning. People often imagine a correlation between events when no such correlation exists. Jennings, Amabile, and Ross (1982) argue that illusory correlation can play an important role in the confirmation of false hypotheses, finding that people underestimate correlation when they have no theory of the correlation, but exaggerate correlation and see it where it is not when they have a preconceived theory of it.

Third, confirmatory bias occurs when people selectively collect or scrutinize evidence. One form of “scrutiny-based” confirmatory bias is what we shall call hypothesis-based filtering. While it is sensible

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8 As Jennings, Amabile, and Ross (1982, p. 212) put it, “even the staunchest defenders of the layperson’s capacities as an intuitive scientist ... have had little that was flattering to say about the layperson’s handling of bivariate observation.”


10 Similarly, Redelmeier and Tversky (1996) argue illusory correlation may help explain the persistent belief that arthritis pain is related to the weather.

11 Another mechanism can be defined as “positive test strategy”: People tend to ask questions (of others, of themselves, or of data) that are likely to be true if their hypothesis is true—without due regard to the fact that they are likely to be true even if the hypothesis is false. See Einhorn and Hogarth (1978), Klaman and Ha (1987), Beattie and Baron (1988), Devine, Hirt, and Gehrke (1990), Hodgins and Zuckerman (1993), Friedrich (1993), and Zuckerman, Knee, Hodgins, and Miyake (1995). We are using this term a bit differently than we suspect psychologists would use it. So far as we know, the term was coined by Klaman and Ha (1987) to point out that much of what was put under the rubric of confirmatory bias could indeed be a rational form of hypothesis testing. Fischhoff and Beyth-Marom (1983, pp. 255-6) and Friedrich (1993) also point out that if people are fully aware that asking “soft” questions teaches them little about the truth of hypotheses, then no bias has occurred. While we feel research on the positive test
to interpret ambiguous data according to current hypotheses, people tend to use the consequent "filtered" evidence inappropriately as further evidence for these hypotheses. If a student gives an unclear answer to an exam question, it is reasonable for a teacher to be influenced in his evaluation of the answer by his prior perceptions of that student’s mastery of the material. However, after assigning differential grades to students according to differential interpretation of comparable answers, it is a mistake to then use differential grades on the exam as further evidence of the differences in the students’ abilities.\(^2\) This sort of error is especially likely when the complexity and ambiguity of evidence requires the use of prior theories when interpreting data and deciding what data to examine.

Finally, one of the main results in our model is confirmation of the conjecture common in the psychological literature that confirmatory bias leads to overconfidence. A vast body of psychological research, separate from research on confirmatory bias, finds that people are prone towards overconfidence in their judgments.\(^3\)

3. Confirmatory Bias and Belief Formation

Consider two states of the world, \(x \in \{A, B\}\), where \(A\) and \(B\) are two exhaustive and mutually exclusive hypotheses regarding some issue. We consider an agent whose prior belief about \(x\) is given by \(\text{prob}(x = A) = \text{prob}(x = B) = 0.5\), so the agent initially views the two alternative hypotheses as equally likely to be true. In every period \(t \in \{1, 2, 3, \ldots\}\) the agent receives a signal, \(s_t \in \{a, b\}\), that is correlated with the true state of the world. Signals received at different times \(t\) are independently and identically

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\(^2\) Lord, Ross, and Lepper (pp. 2106-7) note a similar distinction in reflecting on the bias in their experiment discussed above. They note that it is proper for people to differentially assess probableness of different studies according to their current beliefs about the merits of the death penalty. The “sin” is in using their hypothesis-based interpretations of the strength of different studies as further support for their beliefs.

\(^3\) See, e.g., Oskamp (1982), Mahajian (1992), and Paese and Kinnaly (1993). An early paper that makes this point is Fischhoff, Slovic, and Lichtenstein (1977), who also tested the robustness of overconfidence with monetary stakes rather than reported judgments. No decrease in overconfidence was found relative to the no-money-stakes condition. (As Camerer (1995) notes, there exist very few conclusions reached by researchers on judgment that have been overturned when monetary stakes are added.) There have, however, been criticisms of the evidence in support of overconfidence. See Bjorkman (1994), Pfeifer (1994), Tomassini, Solomon, Romney, and Kroghad (1982), Van Lente (1993), and Winman and Justin (1993). We feel, nevertheless, that the evidence makes a strong case for overconfidence. Indeed, see Soll (1996) for evidence that overconfidence does extend to ecologically valid domains.
distributed, with prob(\(s_t = a | A\)) = \(\text{prob}(s_t = b | B) = \theta\), for some \(\theta \in (0.5, 1)\). After receiving each signal, the agent updates his belief about the relative likelihood of \(x = A\) and \(x = B\).

To model confirmatory bias, we suppose that the agent may misinterpret signals that conflict with his current belief about which hypothesis is more likely. Suppose that, given the signals the agent thinks he has observed in the first \(t-1\) periods, he believes that state \(A\) is more likely than state \(B\). Because of his confirmatory bias, the agent may misread a conflicting signal \(s_t = b\) in the next period, believing instead that he observes \(s_t = a\).

Formally, in every period \(t \in \{1, 2, 3, \ldots\}\) the agent perceives a signal \(\sigma_t \in \{\alpha, \beta\}\). When the agent perceives a signal \(\sigma_t = \alpha\) he believes that he actually received a signal \(s_t = a\), and if he perceives \(\sigma_t = \beta\) he believes that he actually received a signal \(s_t = b\). He updates his beliefs using Bayes’ rule given his (possibly erroneous) perceptions of the signals he is receiving. We assume that with probability \(q > 0\) the agent misreads a signal \(s_t\) that conflicts with his belief about which hypothesis is more likely, and that the agent always correctly interprets signals that confirm his belief. If he currently believes that hypothesis \(A\) is more likely, then for sure he interprets a signal \(s_t = a\) as \(\sigma_t = \alpha\), but with probability \(q\) he misreads \(s_t = b\) as \(\sigma_t = \alpha\).

This model of confirmatory bias incorporates several unrealistic simplifying assumptions. For instance, we assume that the severity of the bias summarized by \(q\) does not depend on the strength of the agent’s beliefs about which of the two states is more likely. It would be reasonable to expect that \(q\) is greater if the agent’s beliefs are more extreme. We conjecture that our qualitative results would continue to hold were we to relax this assumption. Also, we assume that the agent misreads conflicting evidence as confirming evidence. A more realistic alternative model would assume instead that the agent merely has a tendency to overlook evidence that conflicts with his beliefs. This model, too, would yield the same qualitative results as our model.

The presence of confirmatory bias means that the agent’s perceived signals \(\sigma_t\) are neither independently nor identically distributed. Suppose that, after receiving signals \(s^{t-1} = (s_1, \ldots, s_{t-1})\) the agent has perceived a sequence of signals \(\sigma^{t-1} = (\sigma_1, \ldots, \sigma_{t-1})\) and holds beliefs \(\text{prob}(x = A | \sigma^{t-1})\). Define:

\[
\theta^* = \text{prob}(\sigma_t = \alpha | \text{prob}(x = A | \sigma^{t-1}) > 0.5, x = B) = \text{prob}(\sigma_t = \beta | \text{prob}(x = B | \sigma^{t-1}) > 0.5, x = A).
\]

\[
\theta^{**} = \text{prob}(\sigma_t = \alpha | \text{prob}(x = A | \sigma^{t-1}) > 0.5, x = A) = \text{prob}(\sigma_t = \beta | \text{prob}(x = B | \sigma^{t-1}) > 0.5, x = B).
\]

\(\theta^*\) and \(\theta^{**}\) summarize the distribution of the agent’s perceived signal \(\sigma_t\), when the agent believes that one hypothesis is more likely than the other, i.e. when \(\text{prob}(x = A | \sigma^{t-1}) \neq 0.5\). \(\theta^*\) is the probability that the agent perceives a signal confirming his belief that one hypothesis is more likely when in fact the other hypothesis is true. \(\theta^{**}\) is the probability that the agent perceives a signal confirming his belief that a hypothesis is more likely when in fact it is true. Because with probability \(q\) the agent misreads a signal that conflicts with his beliefs, \(\theta^* = (1 - \theta) + q\theta\) and \(\theta^{**} = \theta + q(1 - \theta)\). When \(\text{prob}(x = A | \sigma^{t-1}) = 0.5\), i.e.
when the agent believes that the two possible hypotheses are equally likely, the agent does not suffer from confirmatory bias. In this case, he correctly perceives the signal that he receives, and he updates accurately, so \( \theta = \text{prob}(c_{i} \mid \text{prob}(x = A \mid c_{i}^{-1}) = 0.5, x = A) = \text{prob}(c_{i} \mid \text{prob}(x = B \mid c_{i}^{-1}) = 0.5, x = B) \).

If \( q = 0 \) then the agent is an unbiased Bayesian statistician, while if \( q = 1 \) the agent’s first piece of information completely determines his final belief, since he always misreads signals that conflict with the first signal he receives. More generally, the higher is \( q \), the more extreme is the confirmatory bias.

Suppose that the agent has perceived \( n_{a} \) \( \alpha \) signals and \( n_{b} \) \( \beta \) signals, where \( n_{a} > n_{b} \). Because the agent believes he has received \( n_{a} \) \( \alpha \) signals and \( n_{b} \) \( \beta \) signals, his updated posterior beliefs are given by

\[
\text{prob}(x = A \mid n_{a}, n_{b}) = \frac{\theta^{n_{a} - n_{b}}}{\theta^{n_{a} - n_{b}} + (1 - \theta)^{n_{a} - n_{b}}}. \quad \text{Define } \Lambda(n_{a}, n_{b}) = \frac{\text{prob}(x = A \mid n_{a}, n_{b})}{\text{prob}(x = B \mid n_{a}, n_{b})}. \quad \Lambda(n_{a}, n_{b}) \text{ represents the agent’s beliefs in terms of a relative likelihood ratio. Using Bayes’ Rule, } \Lambda(n_{a}, n_{b}) = \frac{\theta^{n_{a} - n_{b}}}{(1 - \theta)^{n_{a} - n_{b}}}. \quad \text{If } \Lambda(n_{a}, n_{b}) > 1 \text{ the agent believes that } A \text{ is more likely than } B \text{ to be the true state, while if } \Lambda(n_{a}, n_{b}) < 1 \text{ the agent believes that } B \text{ is more likely than } A. \quad \text{If } \Lambda(n_{a}, n_{b}) = 1 \text{ the agent believes that the two states are equally likely. The agent’s interpretation of an additional signal is biased whenever } \Lambda(n_{a}, n_{b}) \neq 1.

In order to identify the effects of confirmatory bias, it is helpful to compare the agent’s beliefs with the beliefs of a hypothetical unbiased, Bayesian observer who learns how many \( \alpha \) and \( \beta \) signals the agent has perceived, and who knows that the agent suffers from confirmatory bias. Like the agent, the Bayesian observer initially believes that \( \text{prob}(x = A) = \text{prob}(x = B) = 0.5 \), and she has no independent information about whether \( x = A \) or \( x = B \). This hypothetical observer’s beliefs, therefore, reflect the true probability that \( x = A \) and \( x = B \), given the signals that the agent has perceived.

Define \( \Lambda^{*}(n_{a}, n_{b}) \) as the Bayesian observer’s likelihood ratio of \( A \) versus \( B \) when she knows that an agent who suffers from confirmation bias has perceived \( n_{a} \) \( \alpha \) signals and \( n_{b} \) \( \beta \) signals, where \( n_{a} > n_{b} \). In general, when \( q > 0 \) the biased agent’s likelihood ratio \( \Lambda(n_{a}, n_{b}) \) and the unbiased observer’s likelihood ratio \( \Lambda^{*}(n_{a}, n_{b}) \) are not equal. If \( \Lambda(n_{a}, n_{b}) > \Lambda^{*}(n_{a}, n_{b}) \) when \( n_{a} > n_{b} \), the agent is overconfident; his belief in favor of the hypothesis that \( x = A \) is stronger than is justified by the available evidence. Similarly, if \( \Lambda(n_{a}, n_{b}) < \Lambda^{*}(n_{a}, n_{b}) \), the agent is underconfident in his belief that \( x = A \).

In the formal results that we develop below, we assume that, while the unbiased observer knows how many \( \alpha \) and \( \beta \) signals the agent has perceived, she does not know the order in which the agent perceived his signals. But when \( q > 0 \) the order of the agent’s perceived signals, if known, would influence a Bayesian observer’s beliefs, since the agent’s confirmatory bias implies that his perceived signals are not distributed independently. Suppose that the agent has perceived three \( \alpha \) signals and two \( \beta \) signals, in which case his beliefs are \( \Lambda(n_{a} = 3, n_{b} = 2) = \theta/(1 - \theta) \). If the Bayesian observer knew the order of the agent’s signals, her posterior belief \( \Lambda^{*}(n_{a} = 3, n_{b} = 2) \) could be less than, greater than, or equal to \( \theta/(1 - \theta) \).
depending on the order of the signals. Thus, from the perspective of an outside observer, the agent could be overconfident, underconfident, or perfectly calibrated in his beliefs.

Suppose, for example, that the Bayesian observer knew that the agent’s sequence of perceived signals was \((\alpha, \beta, \alpha, \alpha, \alpha)\). In this case the observer’s posterior likelihood ratio is:

\[
\Lambda^* = \frac{\theta(\theta + q(1-\theta))^2(1-\theta)^2}{(1-\theta)(1-\theta + q\theta)^2\theta^2} = \frac{\theta + q(1-\theta))^2(1-\theta)}{(1-\theta + q\theta)^2\theta} \leq \frac{\theta}{1-\theta}, \quad \forall q \in (0, 1].
\]

Intuitively, the Bayesian observer recognizes the possibility that the agent may have misread his second and third signals, perceiving that they supported the hypothesis that \(x = A\) when in fact one or both may have supported the hypothesis that \(x = B\). Therefore, the Bayesian observer is less convinced that \(x = A\) than the agent, who is overconfident in his belief. More generally, an observer who knows that a biased agent has always believed in his current hypothesis should judge the agent to be overconfident in his belief, since there is a positive probability that the agent has misread signals that are counter to his favored hypothesis. An observer who knows that a teacher has always believed that Bart is smarter than Marta should recognize that the teacher’s confirmatory bias may have led him to misread evidence that Marta is in fact smarter.

Alternatively, suppose that the Bayesian observer knew that the agent’s sequence of perceived signals was \((\beta, \beta, \alpha, \alpha, \alpha)\). Now the observer’s posterior likelihood ratio is:

\[
\Lambda^* = \frac{(1-\theta)(1-\theta + q\theta)^2\theta^3}{\theta(\theta + q(1-\theta))(1-\theta)^3} = \frac{(1-\theta + q\theta)^2\theta^2}{(\theta + q(1-\theta))(1-\theta)^2} \leq \frac{\theta}{1-\theta}, \quad \forall q \in (0, 1].
\]

In this case, the Bayesian observer believes that the agent may have misread his second signal, perceiving that it supported the hypothesis that \(x = B\) when in fact it may have supported the hypothesis that \(x = A\). Thus, the Bayesian observer believes that there is a greater likelihood that \(x = A\) than the agent, who is underconfident in his belief. More generally, an observer who knows that a biased agent only recently came to believe in his current hypothesis after long believing in the opposite hypothesis should judge the agent to be underconfident in his belief, since the agent may have misread one or more signals that support his current hypothesis when he believed the opposite. An observer who knows that a teacher initially thought that Bart was smarter than Marta, but eventually started to believe that it was slightly more likely that Marta was smarter than Bart, should conjecture that the teacher is underconfident about his new hypothesis. When the teacher believed that Bart was smarter than Marta, he may have misinterpreted signals that Marta was smarter. The fact that the teacher came to believe that Marta was smarter despite his initial bias towards believing that Bart was smarter indicates that the evidence is very strong that Marta is smarter.

The preceding examples illustrate how information about the order of the agent’s signals would significantly influence an outside observer’s judgment about whether, and in what direction, the agent’s beliefs were biased. Nevertheless, for the remainder of the paper we assume that an outside observer only
knows the number of $\alpha$ and $\beta$ signals that the agent has received, and not the order in which he received them. This assumption enables us to identify whether, on average, the agent is over- or underconfident. This appears to be the question that the psychological literature addresses; presumably, it is also of interest to economists.

Clearly, if $q = 0$, then $\Lambda^*(n_\alpha, n_\beta) = \Lambda(n_\alpha, n_\beta)$. When $q > 0$, however, Proposition 1 establishes that $\Lambda^*(n_\alpha, n_\beta) < \Lambda(n_\alpha, n_\beta)$. That is, when the agent perceives that a majority of his signals support (say) hypothesis $A$, he believes in $A$ with higher probability than is warranted.\textsuperscript{14}

**Proposition 1:** Suppose that $n_\alpha > n_\beta$ and $n_\alpha + n_\beta > 1$. Then $\Lambda^*(n_\alpha, n_\beta) < \Lambda(n_\alpha, n_\beta)$.

Proposition 1 establishes that an agent who suffers from confirmatory bias will be overconfident in his belief about which state is most likely.

An observer who knows the agent's beliefs cannot usually observe the exact sequence of the agent's perceived signals. Therefore, the observer's judgment about whether the agent is under- or overconfident depends on her belief regarding the likelihood of the different possible sequences of signals. Proposition 1 establishes that overconfidence is the dominant force. The intuition for this result is fairly straightforward: If you cannot directly observe the agent's past beliefs, but you know that he now believes in hypothesis $A$, you should surmise that, on average, he spent more time in the past believing hypothesis $A$ than hypothesis $B$. Consequently, you should surmise that, on average, the agent misread more signals while believing in hypothesis $A$—consequently to overconfidence—than he misread while believing in hypothesis $B$—contributing to underconfidence. Proposition 1 hinges to some extent on our assumption that the agent receives signals that are the same strength in every period. We believe that (far more complicated) versions of Proposition 1 hold in more general models, but we show in Appendix A that underconfidence is sometimes possible when the agent's signals are of different strengths in different periods.

Proposition 1 shows that when the agent believes that the state is $x = A$ with probability $\mu > 0.5$, the true probability that the state is $x = A$ is less than $\mu$. Interestingly, the true probability that $A$ is the true state may be less than 0.5, meaning that $B$ is more likely than $A$. The possibility that the agent may suffer not merely from overconfidence, but also from "wrongness," arises when the agent's confirmatory bias is severe and he has perceived at least two signals in favor of each hypothesis.

To see the intuition for this result, suppose that the agent has since his first signal $s_1 = \alpha$ believed that hypothesis $A$ is more likely than $B$, but that he nevertheless has perceived two signals $\sigma_t = \sigma_r = \beta$ at two times $t, r > 1$. If the agent's confirmatory bias is severe (i.e. $q \approx 1$), only his first perceived signal in favor of $A$ provides true evidence that $x = A$. Once the agent believes that $A$ is true, his confirmatory bias

\textsuperscript{14} All proofs are in Appendix B. Because our model is entirely symmetric, we shall for convenience present all results and much of our discussion solely for the case where $A$ is perceived as more likely.
predisposes him to perceive that subsequent signals support this belief, and, therefore, additional signals in favor of $A$ are not very informative. But, because the agent’s two perceived signals in favor of $B$ conflict with what he believes—that $x = A$ is more likely—they reflect actual signals in favor of $B$. Thus, although the agent has always believed that $x = A$ is more likely, he has effectively received only one signal in favor of $A$ and two signals in favor of $B$. In this case the agent’s belief that $x = A$ represents extreme overconfidence; had he correctly interpreted evidence, he would believe that $x = B$ is more likely.

It is, of course, possible that hypothesis $A$ is more likely than the agent realizes if he first perceives a signal $s_1 = b$, falsely read $a$’s as $b$’s for a while, and only later perceives enough $a$’s to come to believe in $A$. And it is true that getting more true $a$’s than true $b$’s implies hypothesis $A$ is more likely. Yet it can be shown that these possibilities may be far less likely than the cases leading to extreme overconfidence, so that the net effect is it is more likely that $B$ is true than that $A$ is true if the agent believes in $A$ with mixed evidence.

For example, suppose that the agent has perceived seven signals, 4 $a$’s and 3 $b$’s. Given these signals, the agent’s posterior beliefs are $\Lambda(n_a=4, n_b=3) = \frac{0}{(1 - 0)} > 1$; the agent believes that the state $x = A$ is more likely. Meanwhile, the true likelihood ratio is $\Lambda^*(n_a=4, n_b=3) = \frac{(1 - \theta)^3[8\theta^4 + 8\theta^2 \theta * + 7\theta^2 \theta * * + 3 \theta \theta^2 \theta * * * + \theta \theta^2 \theta * * * *] + (1 - \theta)^2[\theta^2 \theta * * \theta * + 4 \theta^2 \theta * * \theta * ] + 2 \theta^4 (1 - \theta) \theta * *}{\theta^3[8(1 - \theta)^4 + 8(1 - \theta)^3 \theta * + 7(1 - \theta)^2 \theta * * + 5(1 - \theta) \theta^2 \theta * * * + \theta \theta^2 (1 - \theta)^3 \theta * * \theta * + 4(1 - \theta)^4 \theta * * * + 2 \theta (1 - \theta)^4 \theta * * * *]}

Suppose that $\theta = .75$. Then the agent’s posterior likelihood ratio is $\Lambda(4,3) = 3$. Suppose further that $q = .95$, and therefore the agent suffers from severe confirmatory bias. Then, the true likelihood ratio is $\Lambda^*(4,3) = .63$, and therefore $x = B$ is more likely to be the true state, despite the agent having perceived more $a$ signals than $b$ signals.

Indeed, it turns out to be the case that when confirmatory bias is very severe and the signals are very informative, then whenever you observe the agent believing in hypothesis $A$ and having perceived two or more $b$ signals, then you should assume that it is more likely that $B$ is true than $A$. We formalize this in Proposition 2. Let $\Lambda^*(n_a, n_b \mid q, \theta)$ be the appropriate beliefs as a function of $q$ and $\theta$. Then:

**Proposition 2:** For $n_a > n_b$ and $n_b \leq 1$, lim $e \rightarrow 0 \Lambda^*(n_a, n_b \mid 1-e, 1-e) > 1$. For all $n_a > n_b \geq 2$, lim $e \rightarrow 0 \Lambda^*(n_a, n_b \mid 1-e, 1-e) < 1$.

That is, for $\theta$ and $q$ both very close to 1, when the agent has perceived one or fewer $b$ signals and believes in hypothesis $A$, she is probably correct (though overconfident) in her beliefs; when the agent has perceived two or more $b$ signals and believes in hypothesis $A$, she is probably incorrect in her beliefs—hypothesis $B$ is more likely to be true.

We emphasize that the very premise of the proposition means that the situations to which it applies are uncommon; when both $q$ and $\theta$ are close to 1, the probability of perceiving anything besides a
sequence of signals favoring the correct hypothesis is small. Therefore, Proposition 2 tells us about a very low-probability event. For example, in our example with 7 signals, \( q = .95 \), and \( \theta = .75 \), the probability that the signals are sufficiently mixed that the agent is probably wrong is a little more than 1\%.

While we do not know more generally the highest probability with which the agent can be wrong, some calibrations illustrate that it can be relatively likely that the agent ends up with beliefs that a Bayesian observer would deem probably wrong. The tables below display, for various values of \( n \), \( \theta \), and \( q \), the probability that \( \Lambda^* < \eta \) and \( \Lambda > 1 \) or \( \Lambda^* > 1/\eta \) and \( \Lambda < 1 \), where \( \eta \) represents different thresholds for how wrong the agent is. Table entries are in percentage terms (rounded to the nearest percent), with rows corresponding to different values of \( q \) and columns to different values of \( \theta \). (Dashes indicate an entry exactly equal to zero.)

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\( n = 50 \), \( \eta = 1 \)

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\( n = 50 \), \( \eta = 1/9 \)

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\( n = 7 \), \( \eta = 1 \)

For instance, with \( \theta = .6 \) and \( q = .5 \), the probability that the agent has beliefs after 50 signals that the observer would deem probably wrong is about 27\%. The probability in this same case that his beliefs will lead the observer to believe in the other hypothesis with at least probability 2/3 is 19\%, and the probability that the observer would believe in the hypothesis opposite to the agent's with at least probability 3/10 is about 3\%.

---

\( ^{15} \) Readers may note that these probabilities generally increase in \( q \) then decrease, with probability about 0 for \( q = 0 \) and \( q = 1 \). But they are not single-peaked in \( q \). This is because there are two factors at work in

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In the example above and in Proposition 2, the agent can be wrong in her beliefs. Even more surprising, perhaps, the true probability that \( A \) is the correct hypothesis need not be monotonically increasing in the proportion of \( \alpha \) signals the agent perceives. Continue to assume that the agent has received seven signals, but now suppose that five support \( x = A \) and two support \( x = B \). Then, because \( \theta = .75 \), the agent’s posterior likelihood ratio is \( \Lambda(5,2) = 27 > \Lambda(4,3) \). Meanwhile, the true likelihood ratio is:

\[
\Lambda^* (n_\alpha = 5, n_\beta = 2) = \frac{(1-\theta)^2[7(1-\theta)^2 + 90(1-\theta) + 40(1-\theta)^2 + 1 + 7(1-\theta)^2+9(1-\theta)(1-\theta)^2 + 4(1-\theta)^3 + 8(1-\theta)^2 + 8(1-\theta)^3 + 2]}{\theta^2(1-\theta)^2 + 9(1-\theta)(1-\theta)^2 + 4(1-\theta)^3 + 8(1-\theta)^2 + 8(1-\theta)^3 + 2}.
\]

Maintaining the assumption that \( q = .95 \), \( \Lambda^*(5,2) = .62 < \Lambda^*(4,3) = .63 \). Therefore, the relative likelihood that the true state is \( x = A \) versus \( x = B \) is smaller if the agent perceives that five out of seven signals support \( x = A \) than if he perceives that only four out of seven signals support \( x = A \).

While seemingly counterintuitive, this result reflects the fact that the agent is more likely to have perceived (truly informative) signals \( \sigma_j = \beta \) that conflict with a belief that \( x = A \) when he has perceived only two signals in favor of \( B \) than when he has perceived three signals in favor of \( B \). Intuitively, the agent is more likely to have believed for many periods that \( x = A \) in the former case than in the latter case. Put differently, the agent is less likely to have perceived (truly informative) signals \( \sigma_j = \alpha \) that conflict with a belief that \( x = B \) when he has perceived only two signals in favor of \( B \) than when he has perceived three signals in favor of \( B \).

The preceding examples illustrate that an agent who suffers from confirmatory bias may believe that one of the two possible states is more likely than the other when in fact the reverse is true. Nevertheless, Proposition 3 shows that a Bayesian observer who knows only that a biased agent believes that \( x = A \) is more likely than \( x = B \) will herself believe that \( x = A \) is more likely. Therefore, an agent who suffers from confirmatory bias will “on average” correctly judge which of the two possible states is more likely, though, as Proposition 1 establishes, he will always be overconfident in his belief.

Define \( \Lambda^*(n) \) as the likelihood ratio of a Bayesian observer who knows that a confirmatory agent has perceived a total of \( n \) signals, and knows that \( n_\alpha > n_\beta \), but does not know the exact values of \( n_\alpha \) and \( n_\beta \). That is, the observer knows only that the agent believes \( A \) is more likely than \( B \), but observes nothing about the strength of his beliefs. Then:

**Proposition 3:** For all \( n \), \( \Lambda^*(n) > 1 \).

determining the influence of \( q \) on the probability. As \( q \) increases, the probability that the agent will end up with close-to-even mixes of \( \alpha \) and \( \beta \) signals decreases continuously. But because an increase in \( q \) increases the likelihood that any given combination of \( \alpha \)'s and \( \beta \)'s involves the agent being probabilistically wrong, there will be at certain points discrete jumps upward in the likelihood of wrongness for some values of \( q \). The result is an extremely poorly-behaved function.
In light of the above examples where the agent may be wrong, the simple generality of Proposition 3 may seem surprising. It is reconciled with the examples by observing that the agent suffers from “wrongness” only when his confirmatory bias is very severe, meaning that \( q \) is close to 1, and yet he has perceived mixed signals about which state is more likely. But the agent is unlikely to receive mixed signals when his confirmatory bias is strong, because each signal \( \sigma_i \) will tend to mirror \( \sigma_1 \).

4. Beliefs after an Infinite Number of Signals

A fully Bayesian agent—for whom \( q = 0 \)—will after an infinite number of signals come to believe with near certainty in the correct hypothesis. We now investigate the implications of confirmatory bias in the limit as an agent receives an infinite number of signals.

We begin with definitions and a lemma that will help to analyze this question. Suppose that the agent has thus far received \( m = n_a - n_B \) more perceived signals in support of hypothesis \( \Lambda \) than in support of hypothesis \( \Lambda \). Suppose further that, so long as \( n_a > n_B \), \( \text{prob}(\sigma_i = \alpha) = \gamma \). Note that \( \gamma = \theta^* \) if \( \Lambda \) is true, and \( \gamma = \theta^{**} \) if \( \Lambda \) is true. We wish to consider some preliminary results that hold in either case. We define \( p(m, \gamma) \) as the probability that there exists some time in the future the agent will have received an equal number of \( \alpha \) and \( \beta \) signals. (At that time the agent's posterior belief is the same as his prior belief, \( \text{prob}(x = \Lambda) = 0.5 \).) We have the following lemma.

**Lemma 1:** For all \( m > 0 \), \( \gamma \geq 0.5 \), \( p(m, \gamma) = [(1 - \gamma)/\gamma]^m \). For \( \gamma \leq 0.5 \), \( p(m, \gamma) = 1 \).

We define \( P_W \) as the probability that the agent, beginning with the prior belief \( \text{prob}(x = \Lambda) = 0.5 \), comes to believe with certainty in the wrong hypothesis after receiving an infinite number of signals.\(^{16}\)

That is, \( P_W \) is the probability that, although the true state is \( x = \Lambda \), the agent instead comes to believe irreversibly, with near certainty, that \( x = \Lambda \). Proposition 4 characterizes \( P_W \) as a function of \( q \) and \( \theta \):

\[
P_W = \frac{(1 - \theta) \cdot \left(1 - \frac{(1 - \theta^*)}{\theta^*}ight)}{1 - (1 - \theta) \cdot \left(1 - \theta^* \frac{(1 - \theta^{**})}{\theta^{**}}\right)} > 0.
\]

If \( q \leq 1 - 1/(2\theta) \), then \( P_W = 0 \).

Proposition 4: If \( q > 1 - 1/(2\theta) \), then \( P_W = \frac{(1 - \theta) \cdot \left(1 - \frac{(1 - \theta^*)}{\theta^*}ight)}{1 - (1 - \theta) \cdot \left(1 - \theta^* \frac{(1 - \theta^{**})}{\theta^{**}}\right)} > 0 \).

When \( q > 1 - 1/(2\theta) \), \( \theta^* = (1 - \theta) + q\theta > 0.5 \). When \( \theta^* > 0.5 \), then once the agent comes to believe that the wrong hypothesis about \( x \) is more likely, he is consequently more likely to receive a signal \( \sigma_i \) that

\(^{16}\) More formally, \( P_W = \text{Prob}(\forall k > 0 \text{ and } \forall e > 0, \exists n^* \text{ such that } \text{Prob}(n_a - n_B > k \text{ for all } n > n^*) > 1-e) \).
confirms this incorrect belief than he is to receive a signal that conflicts with this incorrect belief. This guarantees that there is a positive probability that the agent will never overturn his incorrect hypothesis, and in fact come to believe more and more strongly in that wrong hypothesis. Conversely, if \( q < 1 - 1/(2\theta) \), then \( \theta^* < .5 \), which guarantees that the agent will, every time he comes to believe the wrong hypothesis is more likely, eventually come to abandon that belief. This in turn implies that the agent will repeatedly come to believe the correct hypothesis is more likely; and since \( \theta^{**} = \theta + q(1-\theta) > \theta > .5 \), he will eventually come to believe in it with near certainty.

The proposition shows that, despite receiving an infinite number of signals, the agent may become certain that the incorrect hypothesis is in fact true.\(^{17}\) This occurs when the agent’s confirmatory bias is sufficiently severe. For example, suppose that \( q = 0.5 \) and \( \theta = .75 \). Then \( P_W = 7/52 \), meaning that 13.5% of the time the agent will eventually come to believe with certainty in the wrong hypothesis. As the quality of the agent’s true signal worsens he is more likely to believe with certainty in the wrong hypothesis. Indeed, a corollary to Proposition 4 is that, fixing any \( q > 0 \), \( \lim_{\theta \to \frac{1}{2}} P_W = \frac{1}{2} \).

We now investigate the related question of when the agent will maintain an incorrect initial belief. To do so, we relax our assumption that the agent initially believes that each state \( x \) is equally likely and suppose instead that the agent initially believes that the wrong hypothesis is more likely to be true. For example, if \( x = B \) is the true state of the world then the agent initially believes \( \text{prob}(x = A) = \mu > 0.5 \). Crucially, we assume that this belief arose from signals that are independent of the new signals that the agent receives, which are distributed as outlined above.

Given the assumption that the signals are independently distributed and ignoring integer problems, these prior beliefs can be interpreted as if the agent has already received \( D \) more signals supporting the incorrect hypothesis, where:

\[
\mu = \frac{\theta^D}{\theta^D + (1-\theta)^D}.
\]

This formula implicitly defines a function \( D(\mu) \). The agent must receive \( D(\mu) \) more conflicting signals \( \sigma_I \) than confirming signals in order to reach a posterior belief that the two possible states of the world, \( A \) and \( B \), are equally likely.

We define \( P_W(\mu) \) as the probability that the agent, beginning with the prior belief \( \mu > 0.5 \) that the wrong hypothesis about the state of the world is true, comes to believe with certainty in the wrong hypothesis after receiving an infinite number of signals.\(^{18}\)

\[^{17}\] It is straightforward to show that the agent becomes certain that the correct hypothesis about the state of the world is true with complementary probability. Therefore, after an infinite number of signals the agent will believe that one of the hypotheses is certainly true.

\[^{18}\] \( P_W(0.5) = P_W \).
Proposition 5: Choose any $\epsilon > 0$ and any $\mu > 0.5$. Then:

(i) For all $\theta \in (0.5,1)$, there exists $q > 0$ such that $P_w(\mu) > 1 - \epsilon$.
(ii) For all $q > 0$, there exists $\theta > 0.5$ such that $P_w(\mu) > 1 - \epsilon$.

Proposition 5 says that an agent who begins with an arbitrarily small bias in the direction of the incorrect hypothesis will almost surely maintain his belief in this hypothesis when either of two conditions is satisfied. First, and not very surprisingly, this will occur when the agent is subject to severe confirmatory bias. When $q$ is very close to 1 then the agent almost never receives signals that conflict with his initial belief, and therefore it is not surprising that this belief is rarely overturned. Second, and somewhat more surprisingly, the agent almost surely maintains his incorrect belief provided that his true signals are very weak, meaning that $\theta$ is very close to 0.5. This result does not depend on the level of confirmatory bias, so long as $q > 0$. This result means that if the agent receives only very weak feedback from his environment and is subject to any confirmatory bias, he almost never overcomes any initial beliefs that are significantly incorrect, and in fact comes to believe that the incorrect hypothesis is certainly true. While one should not overinterpret the second result in Proposition 5—we can question whether agents really pay attention to such weak feedback—the conclusion is nevertheless very striking. Propositions 4 and 5 show that an infinite sequence of signals will not necessarily lead people to overcome erroneous beliefs; rather, people may simply become more and more confident in those erroneous beliefs.

5. Discussion and Conclusion

We believe that confirmatory bias is important in many social and economic situations, and that variants of the formulation developed in this paper can be usefully applied in formal economic models. One possible application is to a principal-agent model. Confirmatory bias may lead agents to take undesirable actions not solely because of “moral hazard” problems, but also because they are overconfident. Beyond making sure that people live with the negative consequences of bad choices, therefore, incentives should also be designed to prevent decisions based on good-faith overconfidence. For instance, at a conference one of the authors attended, a leading economist conjectured that bad investment decisions by businesses in Eastern Europe receiving bank loans were more often the result of overconfidence by borrowers than of intentions to mislead banks.$^{19}$ We hope applications of our model can help economists formally analyze such a claim, rather than relegating it to the category of informal intuitions that have no place in mainstream research.

$^{19}$ Relatedly, Wood (1989) asserts that money managers become more confident in their investment decisions as they gather more information—even when the quality of their investment decisions are not improved.
Another potential area of application concerns how a decision-maker aggregates information from many sources. In a setting where several individuals (non-strategically) report their beliefs to a principal, how should she combine their beliefs to form her own beliefs? If the principal thought the agents were Bayesians, then she would be very sensitive to how strong the agents’ beliefs are. Suppose, for instance, that the principal knows that all agents receive signals of strength $\theta = .6$. Then if two agents report believing hypothesis $A$ with probability .6 and one agent reports believing hypothesis $B$ with probability .77 (meaning he has gotten three more $b$ signals than $a$ signals), the principal should believe in Hypothesis $B$ with probability .6.

What if the principal were aware that agents are subject to confirmatory bias? One intuition is that if confirmatory bias is severe, so that only the first signal each agent gets is informative to the principal, then the agent should discount the strength of agents’ beliefs, and basically aggregate according to a “majority rules” criterion. In the example above, for instance, the principal should perhaps think Hypothesis $A$ is more likely, because two of three agents believe in it. We think this intuition has merit, but it is complicated by the fact that agents who believe relatively weakly in a hypothesis may be more likely to be wrong than right. So, if the principal thought confirmatory bias were severe and were very sure that all agents had received lots of information, then in our example she should believe all three agents have provided evidence in favor of Hypothesis $B$. Hence, she should believe more in Hypothesis $B$ than she would if the agents were Bayesian.  

In many contexts, we suspect that usefully incorporating confirmatory bias into economic analysis will depend upon assumptions about judgment whose psychological validity has not (to our knowledge) been determined by research. For instance: Do people believe that others suffer from the bias? It could be that people are well aware of biases in others’ judgment, or that people are unaware of the general tendency towards confirmatory bias. Investors who hire a money manager might or might not believe that the money manager suffers from a confirmatory bias (and is therefore prone towards overconfidence). A principal hiring an employee to make decisions might or might not know that the employee will be prone to making such errors. By the logic of economic models that involve multiple agents, these

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20 We do suspect that the “majority-rules intuition” is more valid, especially when considering realistic uncertainty by the principal about how many signals each agent has received. If she were highly uncertain how much information each agent received, she would assume weak beliefs merely reflected that an agent got few signals. Similarly, if the principal thinks susceptibility to confirmatory bias is heterogeneous, she might infer that an agent’s weak beliefs indicates merely that he is not susceptible to overconfidence, and count weak beliefs as much as strong beliefs. Indeed, she may then count them more heavily, since confirmation-free agents are not only less likely to be overconfident, they are also less likely to be wrong.

21 Unfortunately, while this issue may turn out to be central to economic applications of confirmatory bias (and to applications of other psychological biases), we have not found psychological research that convincingly resolves this issue. There is a small literature in “construal” that concerns third-party awareness of biases. See, e.g., Ross (1987), and tangentially Paese and Kinnaly (1993). We have not found investigation of this issue in the context of confirmatory bias or overconfidence.
distinctions are likely to matter. Just as assuming that rationality is common knowledge is often very different than merely assuming that people are rational, assuming that agents are aware of others’ irrationality may be very different than merely assuming that people are irrational.

How might economic implications depend on people’s awareness of others’ confirmatory bias? One possibility is that people might exploit the bias of others. A principal may, for instance, design an incentive contract for an agent that yields the agent lower wages on average than the agent anticipates, because the agent will be overconfident about her judgments in ways that may lead her to exaggerate her yield from a contract. Conversely, others may wish to mitigate bias rather than exploit it. A principal may be more concerned with overcoming costly bias of an agent than with exploiting it, and design contracts that avoid errors.

Appendix A: Differential-Strength Signals and Underconfidence

If the agent receives signals of different strengths in different periods, it is possible that the agent will be underconfident in his belief about which of the two states is most likely. Suppose, for example, that the agent receives three signals \( s_t \in \{a, b\}, \ t \in \{1, 2, 3\} \). Suppose that the first two signals are distributed according to \( \text{prob}(s_t = a|A) = \text{prob}(s_t = b|B) = \theta > 0.5, \ t \in \{1, 2\} \), but that the agent’s third signal is distributed according to \( \text{prob}(s_3 = a|A) = \text{prob}(s_3 = b|B) = \frac{\theta^3}{\theta^3 + (1 - \theta)^3} \). That is, the agent’s third signal is three times as strong as first- or second-period signals. As before, with probability \( q > 0 \) the agent misreads signals that conflict with his belief about which state is more likely. (This means that the probability of misreading is independent of the strength of the signal.)

Suppose that the agent perceives that his first two signals support hypothesis \( B \), while his third signal supports hypothesis \( A \). Formally, the agent perceives \( (\sigma_1 = \beta, \sigma_2 = \beta, \sigma_3 = \alpha) \). Given these perceived signals, the agent’s posterior likelihood ratio is \( \Lambda(s_1 = b, s_2 = b, s_3 = a) = \theta/(1 - \theta) > 1 \). Now, suppose that a Bayesian observer knows both that the agent’s posterior likelihood ratio is \( \Lambda = \theta/(1 - \theta) \) and that the agent suffers from confirmatory bias. Given the distributions of the signals, the observer is able to infer that the agent has perceived \( (\sigma_1 = \beta, \sigma_2 = \beta, \sigma_3 = \alpha) \). Then, the observer’s belief regarding the relative likelihood that the state is \( x = A \) versus \( x = B \) is given by:

\[
\Lambda^*(b, \beta, \alpha) = \frac{(1 - \theta)(1 - \theta + q\theta)(1 - q)\theta^3}{\theta(\theta + q(1 - \theta))(1 - q)(1 - \theta)^3} = \frac{(1 - \theta + q\theta)\theta^2}{(\theta + q(1 - \theta))(1 - \theta)^2} > \frac{\theta}{1 - \theta}, \forall q \in (0,1].
\]

20
Therefore, given what she infers about the agent's sequence of perceived signals, a Bayesian observer believes that the biased agent is underconfident in his belief that the true state is \( A \).

This underconfidence result arises here because the observer infers the exact sequence of the agent's perceived signals from his likelihood ratio. In this light, the results here are the same as the path-dependent underconfidence example in the text—if the agent is known to have only recently come to believe in a hypothesis, then he will be underconfident. In our main model, in which the agent receives signals of equal strength, an observer who knows the agent's beliefs cannot infer the exact sequence of the agent's perceived signals.

While there may be some domains in which this differential-signal model is applicable, constructing examples of underconfidence seem to require clever contrivance. It is first of all clear that the "overconfidence" result will be stronger than the underconfidence result in one sense: In the model of this paper, the overconfidence result holds for all final beliefs by the agent. Any underconfidence example will clearly hold for only some final beliefs—because it will always be the case that a confirmatory agent is overconfident when all his perceived signals favor one hypothesis.

We suspect, moreover, that more complicated and weaker versions of Proposition 1 will hold in more general models. The underconfidence result seems to rely on the agent having received a small number of signals, where certain final beliefs can only be generated by a unique path of updating. Consequently, it is very likely that a "limit overconfidence" result would hold—once an agent is likely to have received large numbers of signals of all strengths, we can assure \( \Lambda^* < \Lambda \) when \( \Lambda > 1 \).

**Appendix B: Proofs**

**Proof of Proposition 1:** We first notice that

\[
\begin{align*}
\text{prob}(n_a, n_b | A) &= \sum_{i=0}^{n_a} \text{prob}(i, i | A) c_i [\theta + q(1 - \theta)]^{n_a-i} (1 - q)^{n_a-i} (1 - \theta)^{n_b-i} \\
\text{prob}(n_a, n_b | B) &= \sum_{i=0}^{n_a} \text{prob}(i, i | B) c_i (1 - \theta) [(1 - \theta) + q\theta]^{n_a-i} (1 - q)^{n_a-i} \theta^{n_b-i}
\end{align*}
\]

where \( c_i \) is the number of ways to choose \( n_a - n_b \) more \( a \) signals than \( b \) signals in \( n_a + n_b - 2i \) draws without ever having chosen an equal number of \( a \) and \( b \) signals, and \( \text{prob}(i, i | x) \) is the probability of observing \( i \) perceived \( a \) and \( i \) perceived \( b \) signals in \( 2i \) draws when the true state is \( x \in \{A, B\} \). Given the symmetric distribution of the signals, \( \text{prob}(i, i | A) = \text{prob}(i, i | B) \).

Using Bayes' Rule,

\[
\Lambda^*(n_a, n_b) = \frac{\sum_{i=0}^{n_a} \text{prob}(i, i | A) c_i [\theta + q(1 - \theta)]^{n_a-i} (1 - q)^{n_a-i} (1 - \theta)^{n_b-i}}{\sum_{i=0}^{n_a} \text{prob}(i, i | B) c_i (1 - \theta) [(1 - \theta) + q\theta]^{n_a-i} (1 - q)^{n_a-i} \theta^{n_b-i}}
\]
Because \( \frac{\theta + q(1-\theta)}{(1-\theta) + q\theta} \leq \frac{\theta}{1-\theta} \forall q \in (0,1) \) it follows that:

\[ (1.2) \quad \theta + q(1-\theta)\theta^{-i} \leq (1-\theta) + q\theta \theta^{-i} \]

with a strict inequality for \( i = 0 \) since the hypotheses imply that \( n_a \geq 2 \). Factoring and multiplying (1.2) by \( (1-\theta)(1-q)\theta^{-i} \) and rearranging, we have:

\[ (1.3) \quad \theta(1-\theta)(1-q)\theta^{-i} \leq (1-\theta) + q\theta \theta^{-i} \]

\( \forall i \), with a strict inequality for at least \( i = 0 \) since \( n_a \geq 2 \). Using (1.1), (1.3) and \( \text{prob}(i,i|A) = \text{prob}(i,i|B) \):

\[ \Lambda^*(n_a,n_b) = \frac{\sum_{i=0}^{n_a} \text{prob}(i,i|A)\theta^{(1-\theta)(1-q)\theta^{-i} \theta^{-i}}} {\sum_{i=0}^{n_b} \text{prob}(i,i|B)\theta^{(1-\theta)(1-q)\theta^{-i} \theta^{-i}}} = \Lambda(n_a,n_b) \]

\( \text{QED} \)

**Proof of Proposition 2:** Clearly \( \lim_{n_a \to \infty} \Lambda^*(n_a,0) = \infty \forall n_a > 0 \).

\[ \lim_{n_a \to \infty} \Lambda^*(n_a,1) = (n_a+1)/(n_a-1) \forall n_a > 1 \]

It can be shown that, if the agent's current beliefs are that

\( A \) and \( B \) are equally likely, and \( A \) is true, then the probability that the next signal is \( \alpha = 1 \) is \( \beta = \varepsilon \)

\( B \) is true, ...

\( A \) is truly true, ...

\( B \) is true, ...

\( \alpha = 1 \) is \( \varepsilon^{2} \}

\( \approx 1 \) is \( \varepsilon^{2} \}

\( \approx 1 \) is \( \varepsilon \}

\( \approx 1 \) is \( \varepsilon \}

From these numbers we can calculate that, if \( n_a > n_B \):

- Suppose \( A \) is the true state. Consider all paths \( \sigma^* \) such that (1) \( \sigma_1^* = \beta \) and (2) there is always a strict majority of \( \beta \) signals until \( 2n_B-1 \) signals, after which all signals are \( \alpha \). Then the probability of any particular path \( \sigma^* \) is about \( \varepsilon^{n_a-1} \). All other paths each occur with probability on the order of \( \varepsilon^{n_a-2} \) or greater when \( n_B \geq 2 \).

- Suppose \( B \) is the true state. Consider all paths \( \sigma^* \) such that (1) \( \sigma_1^* = \alpha \) and (2) there is always a strict majority of \( \alpha \) signals. The probability of any particular path \( \sigma^* \) is about \( \varepsilon^{n_a-1} \). All other paths each occur with probability on the order of \( \varepsilon^{n_a-2} \) or greater when \( n_B \geq 2 \).

To show \( \Lambda^*(n_a,n_B) < 1 \) with \( n_B \geq 2 \), therefore, we need only to show that the number of paths of type \( \sigma^* \) is strictly greater than the number of paths of type \( \sigma^* \). This is easy to verify. For every particular path of type \( \sigma^* \), there exists a path of type \( \sigma^* \) that is the mirror image of that path for the first \( 2n_B-1 \) signals (replacing each \( \alpha \) with a \( \beta \) and each \( \beta \) with an \( \alpha \)), and whose last \( n_a-n_B+1 \) signals consist of \( \alpha \)'s followed by \( \beta \)'s. In addition, there will exist at least one more path of type \( \sigma^* \); for instance, \( n_a \alpha \)'s followed by \( n_B \beta \)'s.

\( \text{QED} \)

**Proof of Proposition 3:** The proof is by induction. Suppose that \( \Lambda(1) > 1 \). Then a Bayesian observer infers that the agent observed a single true \( "a" \) signal, and \( \Lambda^*(1) = 0/(1-0) > 1 \). Now suppose that \( \Lambda(n) \), \( \Lambda^*(n) \), and \( \Lambda(n+1) > 1 \). We must show that \( \Lambda^*(n+1) > 1 \). First, suppose \( n \) is an even number. Because \( \Lambda(n) > 1 \), after period \( n \) the agent has perceived at least two more \( "a" \) signals than \( "b" \) signals. Therefore, knowing only that \( \Lambda(n) > 1 \), a Bayesian observer's relative likelihood ratio, \( \Lambda^*(n) = \text{prob}(x=A)/\text{prob}(x=B) \), is given by:

22
\[
\begin{align*}
\sum_{j=0}^{n-1} \sum_{i=0}^{j} p(i,i|A)c_i \theta_j q(1-\theta_j) - q^{1-j-i} (1-q)^{1-j-i} (1-\theta_j)^{1-i} \\
\sum_{j=0}^{m-1} \sum_{i=0}^{j} p(i,i|B)c_i (1-\theta_j) [q(1-\theta_j) + q\theta_j] q^{1-j-i} (1-q)^{1-j-i} \theta_j^{1-i}
\end{align*}
\]

(2.1) \( \Lambda^*(n) = \frac{p^A(n)}{p^B(n)} \)

where \( p(i,i|x) \) and \( c_i \) are defined as in the proof of Proposition 1. Define \( p'(n) \) as the probability of receiving a majority of "a" signals in \( n \) draws given the state \( x \in \{A, B\} \). Then \( \Lambda^*(n + 1) \) is given by:

(2.2) \( \Lambda^*(n + 1) = \frac{p^A(n) + p\left(\frac{n}{2}, \frac{n}{2} | A\right)}{p^B(n) + p\left(\frac{n}{2}, \frac{n}{2} | B\right)} \)

Because \( p\left(\frac{n}{2}, \frac{n}{2} | A\right) = p\left(\frac{n}{2}, \frac{n}{2} | B\right) \) and \( \theta > 0.5 \), \( \Lambda^*(n + 1) > 1 \) follows immediately from the hypothesis that \( \Lambda^*(n) > 1 \), which implies that \( p'(n) > p^B(n) \).

Now suppose that \( n \) is an odd number. Because by hypothesis \( \Lambda(n) > 1 \), after period \( n \) the agent has perceived more "a" than "b" signals. Therefore, knowing only that \( \Lambda(n) > 1 \), a Bayesian observer’s relative likelihood ratio, \( \Lambda^*(n) = \text{prob}(x = A) / \text{prob}(x = B) \), is given by:

(2.3) \( \Lambda^*(n) = \frac{p^A(n)}{p^B(n)} \)

Meanwhile, \( \Lambda^*(n + 1) \) is given by:

(2.4) \( \Lambda^*(n + 1) = \frac{p^A(n) + \sum_{i=0}^{n-1} p(i,i|A)c_i \theta_j q(1-\theta_j) - q^{1-j-i} (1-q)^{1-j-i} (1-\theta_j)^{1-i} (1-q)(1-\theta)}{p^B(n) + \sum_{i=0}^{n-1} p(i,i|B)c_i (1-\theta_j) [q(1-\theta_j) + q\theta_j] q^{1-j-i} (1-q)^{1-j-i} \theta_j^{1-i}} \)

Because \( \Lambda^*(n) > 1 \) implies \( p'(n) > p^B(n) \), in order to establish \( \Lambda^*(n+1) > 1 \) it is sufficient to show that:

(2.5) \( \sum_{i=0}^{n-1} p(i,i|A)c_i \theta_j q(1-\theta_j) - q^{1-j-i} (1-q)^{1-j-i} (1-\theta_j)^{1-i} (1-q)(1-\theta) \leq \sum_{i=0}^{n-1} p(i,i|B)c_i (1-\theta_j) [q(1-\theta_j) + q\theta_j] q^{1-j-i} (1-q)^{1-j-i} \theta_j^{1-i} (1-q) \theta \)

Using the fact that \( p(i,i|A) = p(i,i|B) \) and canceling like terms, the inequality in (2.5) is satisfied if \( [\theta + q(1-\theta)]^{1-i} (1-\theta)^{1-i} \leq [1-\theta + q\theta]^{1-i} \theta_j^{1-i} \forall i \in \{0, \ldots, \frac{n-1}{2}\} \). But this inequality is always satisfied because \( \frac{\theta + q(1-\theta)}{1-\theta + q\theta} < \frac{\theta}{1-\theta} \forall \theta \in (0,1] \). Therefore, \( \Lambda^*(n+1) > 1 \).

QED

Proof of Lemma 1: Here we suppress the dependence of \( p(m, \gamma) \) on \( \gamma \) to conserve notation.

Clearly

1. \( p(1) = \gamma p(2) + (1 - \gamma) \)

2. \( p(2) = \gamma p(3) + (1 - \gamma) p(1) \)

... 

\( m \quad p(m) = \gamma p(m+1) + (1 - \gamma) p(m-1) \)
Summing (1) - (m), we obtain
\[
\sum_{m=1}^{\infty} p(m) = \gamma \sum_{m=1}^{\infty} p(m) - \gamma p(1) + (1 - \gamma) \sum_{m=1}^{\infty} p(m) + (1 - \gamma)
\]
or
\[
\sum_{m=1}^{\infty} p(m) = \sum_{m=1}^{\infty} p(m) - \gamma p(1) + (1 - \gamma)
\]
So, \( p(1) = (1 - \gamma)/\gamma \). The general formula for \( p(m) \) is derived by induction, using the fact that for all \( m \) we have \( p(m) = p(m - 1)/\gamma - ((1 - \gamma)/\gamma)p(m - 2) \).

**Proof of Proposition 4:** The first hypothesis implies that \( \theta^* > 0.5 \) and therefore, using Lemma 1, \( P_W \) satisfies
\[
P_W = (1 - \theta) \cdot (1 - p(1, \theta^*)) + p(1, \theta^*) \cdot P_W + \theta \cdot [p(1, \theta^{**}) \cdot P_W],
\]
or
\[
P_W = \frac{(1 - \theta) \cdot (1 - \theta^*)}{1 - (1 - \theta) \cdot (1 - \theta^*) - \theta (1 - \theta^{**})}
\]
\( P_W > 0 \) because \( \theta^{**} > 0.5 \) for all \( q \geq 0 \).

The second hypothesis implies that \( \theta^* \leq 0.5 \) and therefore, using Lemma 1, \( P_W \) satisfies:
\[
P_W = (1 - \theta) \cdot P_W + \theta \cdot [p(1, \theta^{**}) \cdot P_W]
\]
\( P_W = 0 \) because \( p(1, \theta^{**}) < 1 \).

**Proof of Proposition 5:** Ignoring integer problems, and since \( q > 1 - 1/(2/\theta) \) for the cases we consider below, the definition of \( D(\mu) \) and Lemma 1 imply that:
\[
P_W(\mu) = \left( 1 - \left\lfloor \frac{1 - \theta^*}{\theta^*} \right\rfloor \right)^{D(\mu)} + \left\lfloor \frac{1 - \theta^*}{\theta^*} \right\rfloor^{D(\mu)} P_W(0.5) > 0.
\]

(i) Note that \( \lim_{\gamma \to 1} \theta^* = 1 \) for all \((\mu, \theta)\). Therefore, for \( q \) sufficiently close to 1, \( P_W(\mu) \) can be made arbitrarily close to 1.

(ii) Note that \( \lim_{\gamma \to 0.5} \theta^* > 0.5 \) and \( \lim_{\gamma \to 0.5} D(\mu) = \infty \) for all \((\mu, q)\). Therefore, for \( \theta \) sufficiently close to 0.5, \( P_W(\mu) \) can be made arbitrarily close to 1.

\[QED\]
References


